

CS769 Advanced NLP

Multimodal Machine Learning: Vision-Language

Junjie Hu



Slides adapted from LP Morency
<https://junjiehu.github.io/cs769-spring22/>

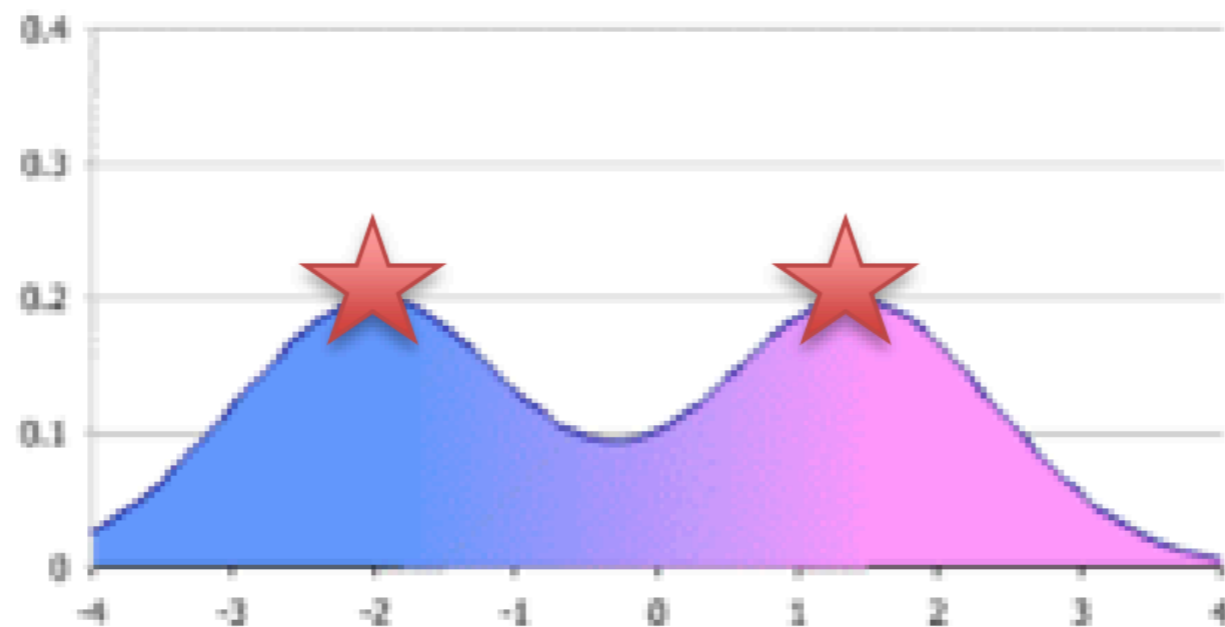
Goal for Today

- What is Multimodal?
 - Historical view, multimodal vs multimedia
- Core technical challenges
 - Representation learning, translation, alignment, fusion, and co-learning
- Recent pre-trained V+L models
 - CLIP
 - DALL-E

Multimodal Machine Learning

What is Multimodal?

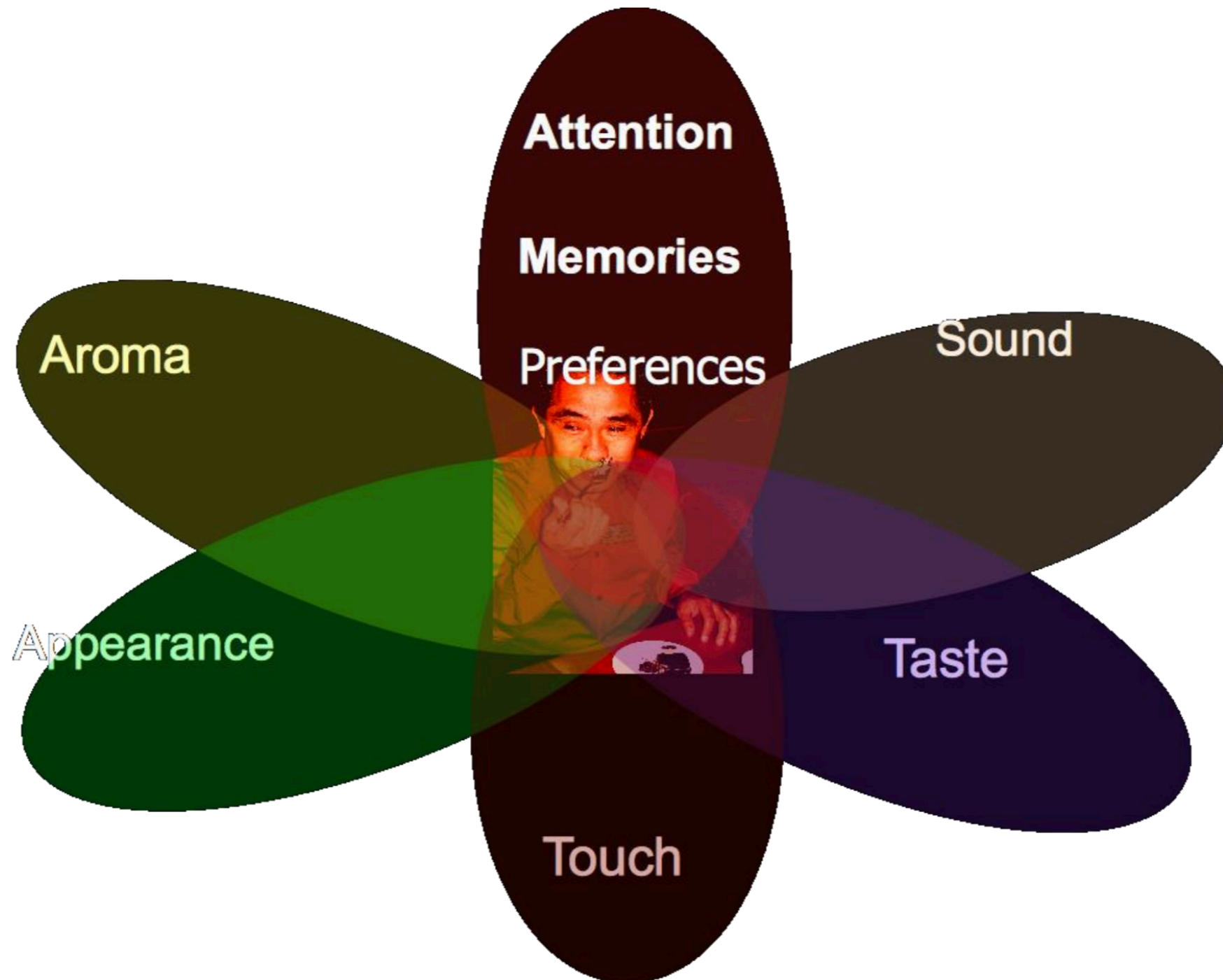
- Multiple modes, i.e., distinct “peaks” (local maxima) in the probability density function



Multimodal distribution

What is Multimodal?

Sensory Modalities



Multimodal Communicative Behaviors

Verbal

Lexicon

Words

Syntax

Part - of - speech

Dependencies

Pragmatics

Discourse acts

Vocal

Prosody

Intonation

Voice quality

Vocal expressions

Laughter, moans

Visual

Gestures

Head gestures

Eye gestures

Arm gestures

Body language

Body posture

Proxemics

Eye contact

Head gaze

Eye gaze

Facial expressions

FACS action units

Smile, frowning

What is Multimodal?

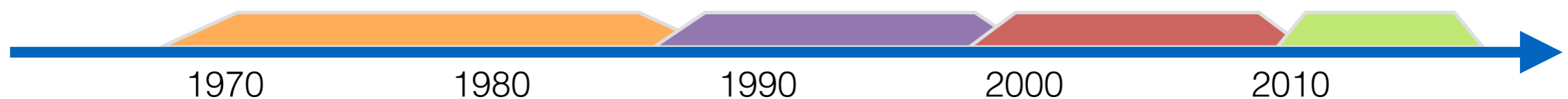
- **Modality**: The way in which something happens or is experienced.
 - Modality refers to a certain type of information and/or the representation format in which information is stored.
 - Sensory modality: one of the primary forms of sensation, as vision or touch; channel of communication.
- **Medium** (“middle”): A **means** or instrumentality for storing or communicating information; system of communication/transmission.
 - Medium is the means whereby this information is delivered to the senses of the interpreter.

Examples of Modalities

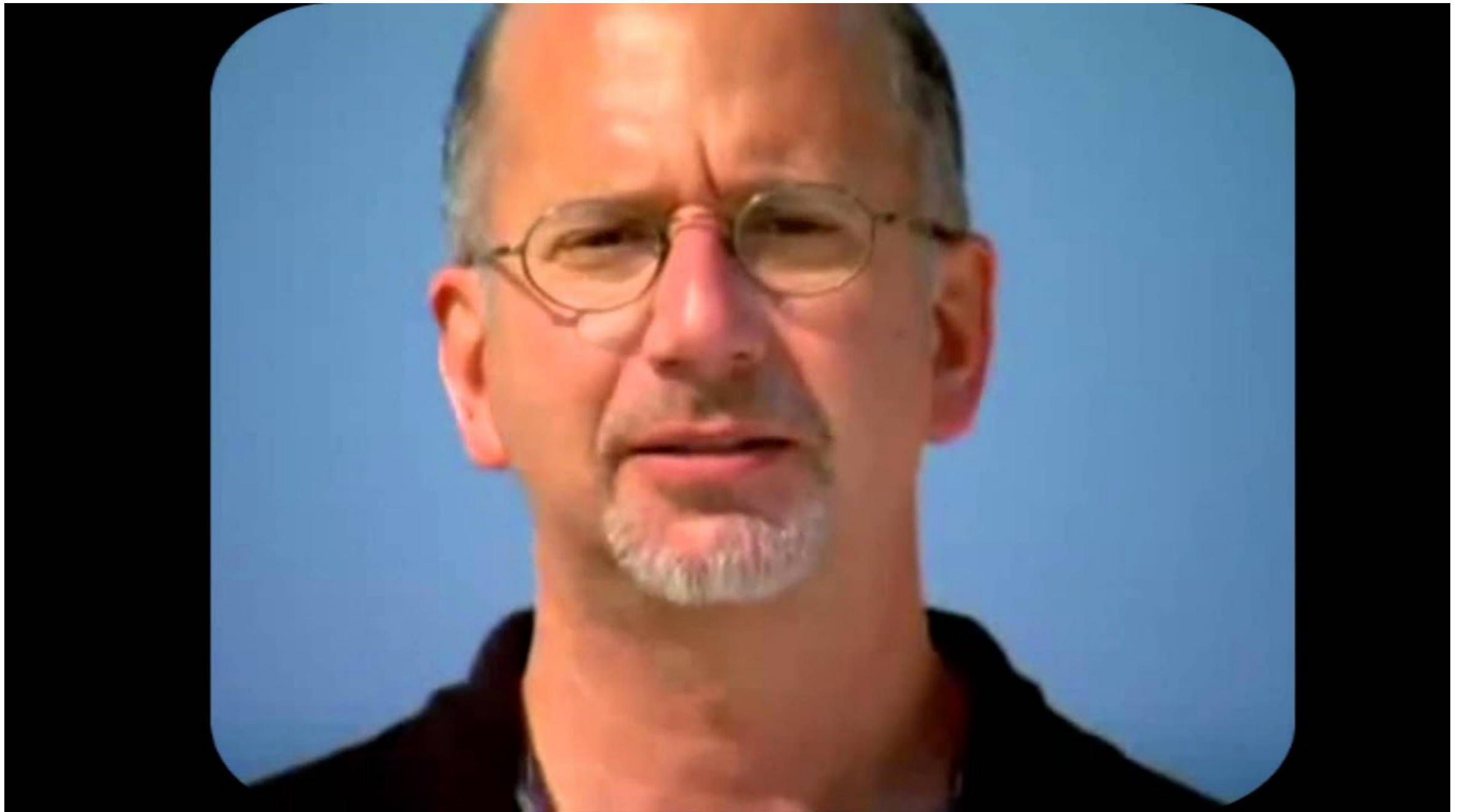
- Natural language (both spoken or written)
- Visual (from images or videos)
- Auditory (including voice, sounds, and music)
- Haptics / touch
- Smell, taste and self-motion
- Physiological signals
 - Electrocardiogram (ECG), skin conductance
- Other modalities
 - Infrared images, depth images, fMRI

Prior Research on “Multimodal”

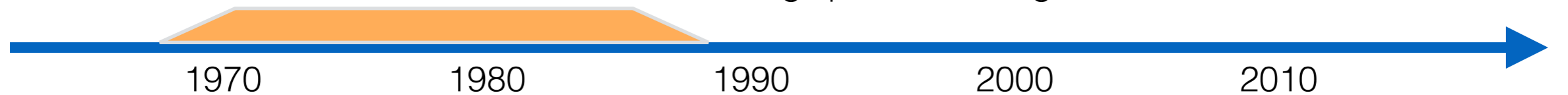
- Four eras of multimodal research
 - The “behavioral” era (1970s until late 1980s)
 - The “computational” era (late 1980s until 2000)
 - The “interaction” era (2000 - 2010)
 - The “deep learning” era (2010s until ...)



The McGurk Effect (1976)

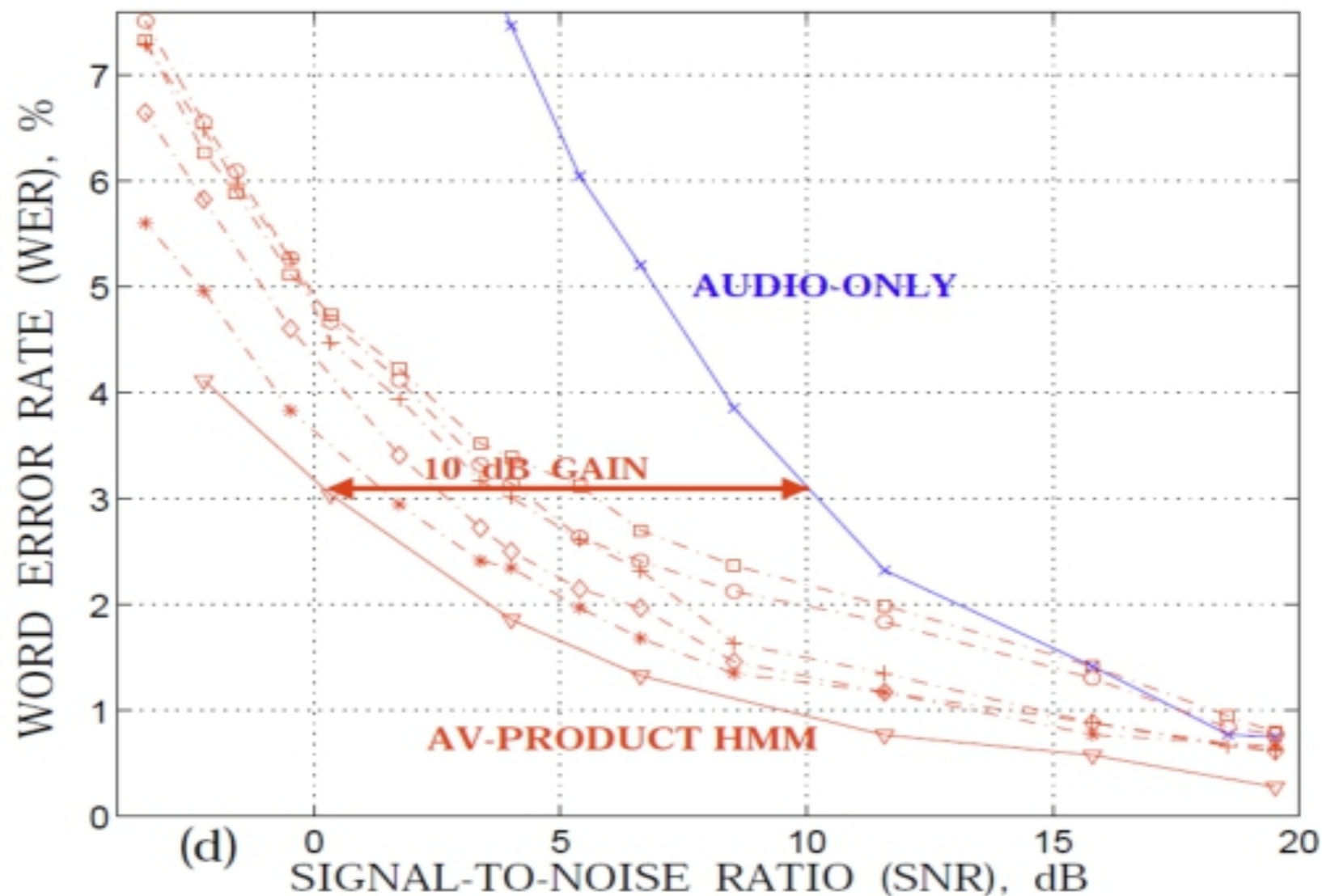


McGurk & MacDonald, 1976. Hearing lips and seeing voices, Nature



The “Computational” Era (Late 1980s until 2000)

- Audio-Visual Speech Recognition (AVSR)



Core Technical Challenges

Core Challenges in “Deep” Multimodal ML (Baltrusaitis et al. 2017)

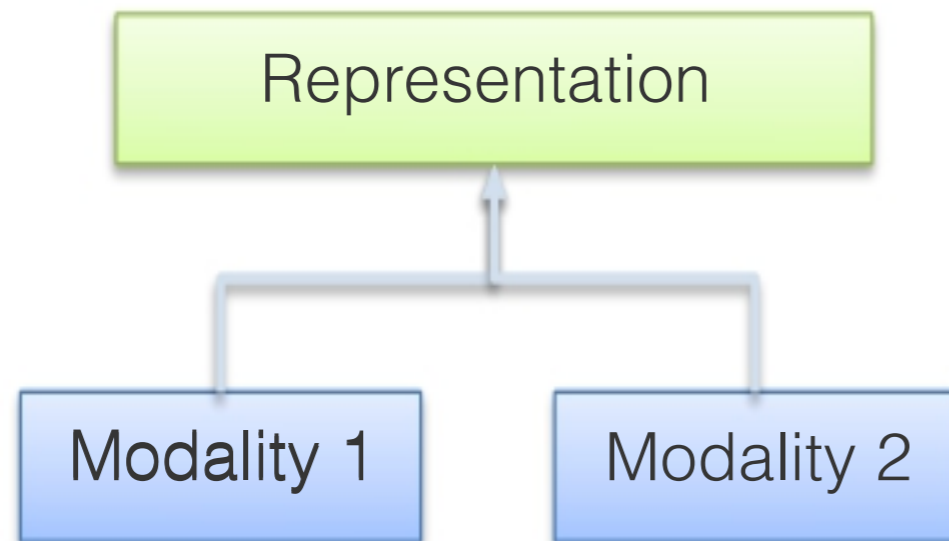
- Representation
- Alignment
- Fusion
- Translation
- Co-Learning

These challenges are non-exclusive.

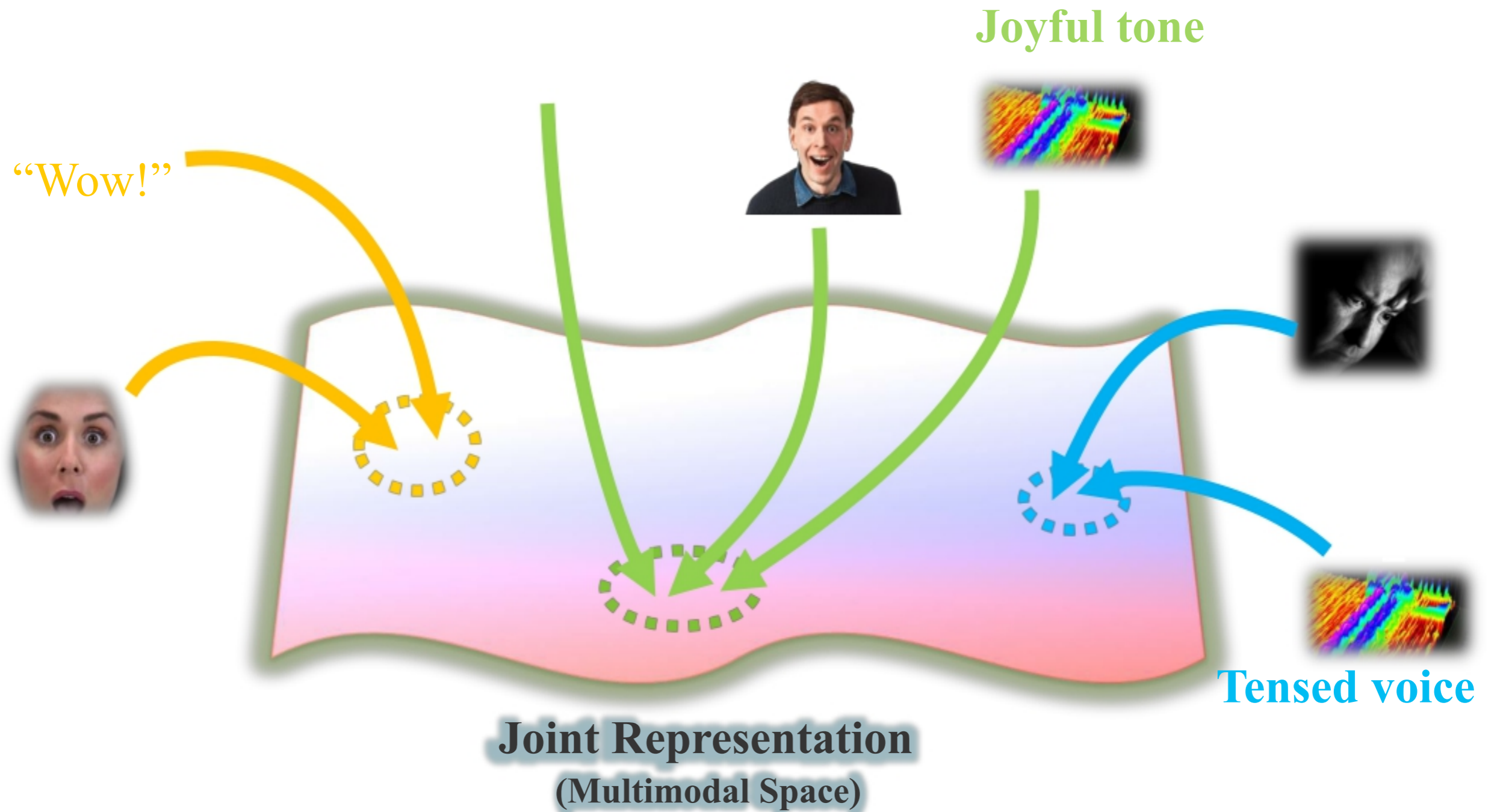
Core Challenge 1: Representation

- **Definition:** Learning how to represent and summarize multimodal data in a way that exploits the complementarity and redundancy.

A Joint representations:

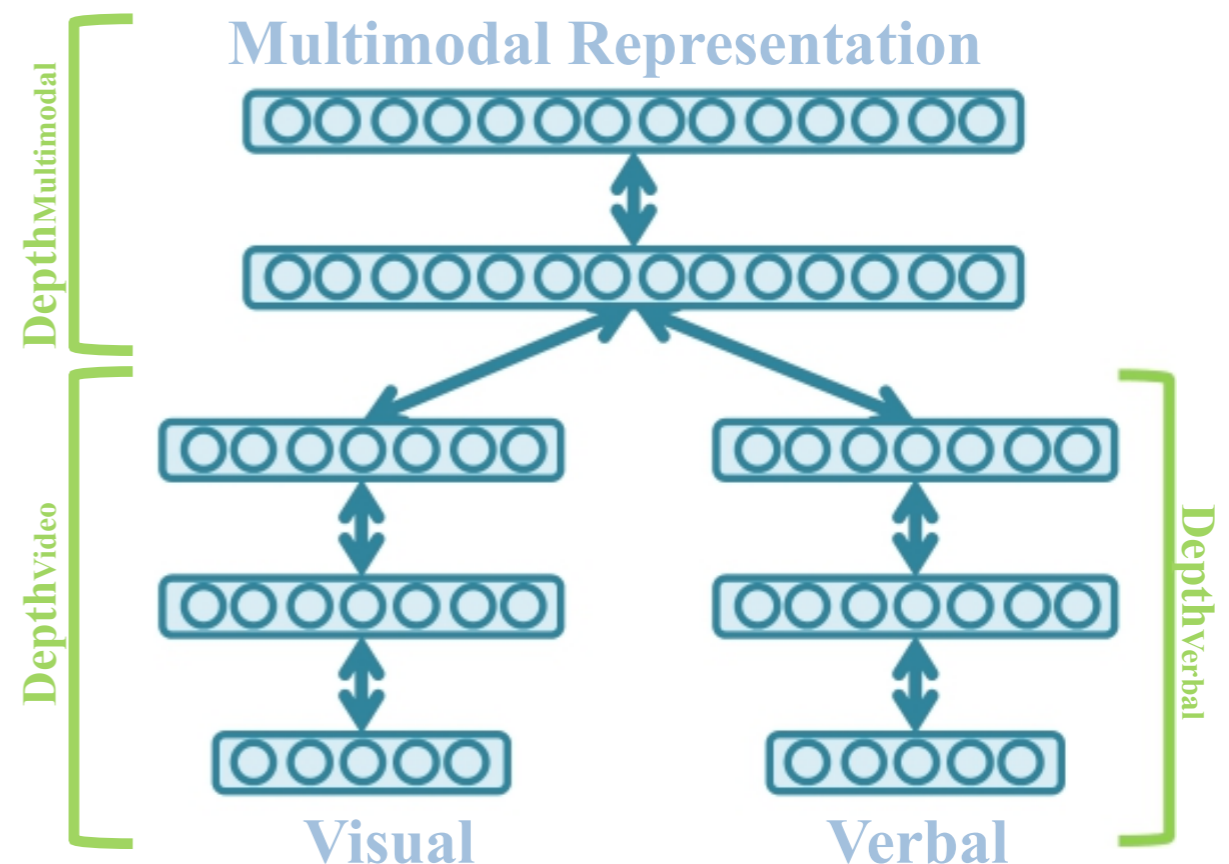


Joint Multimodal Representations



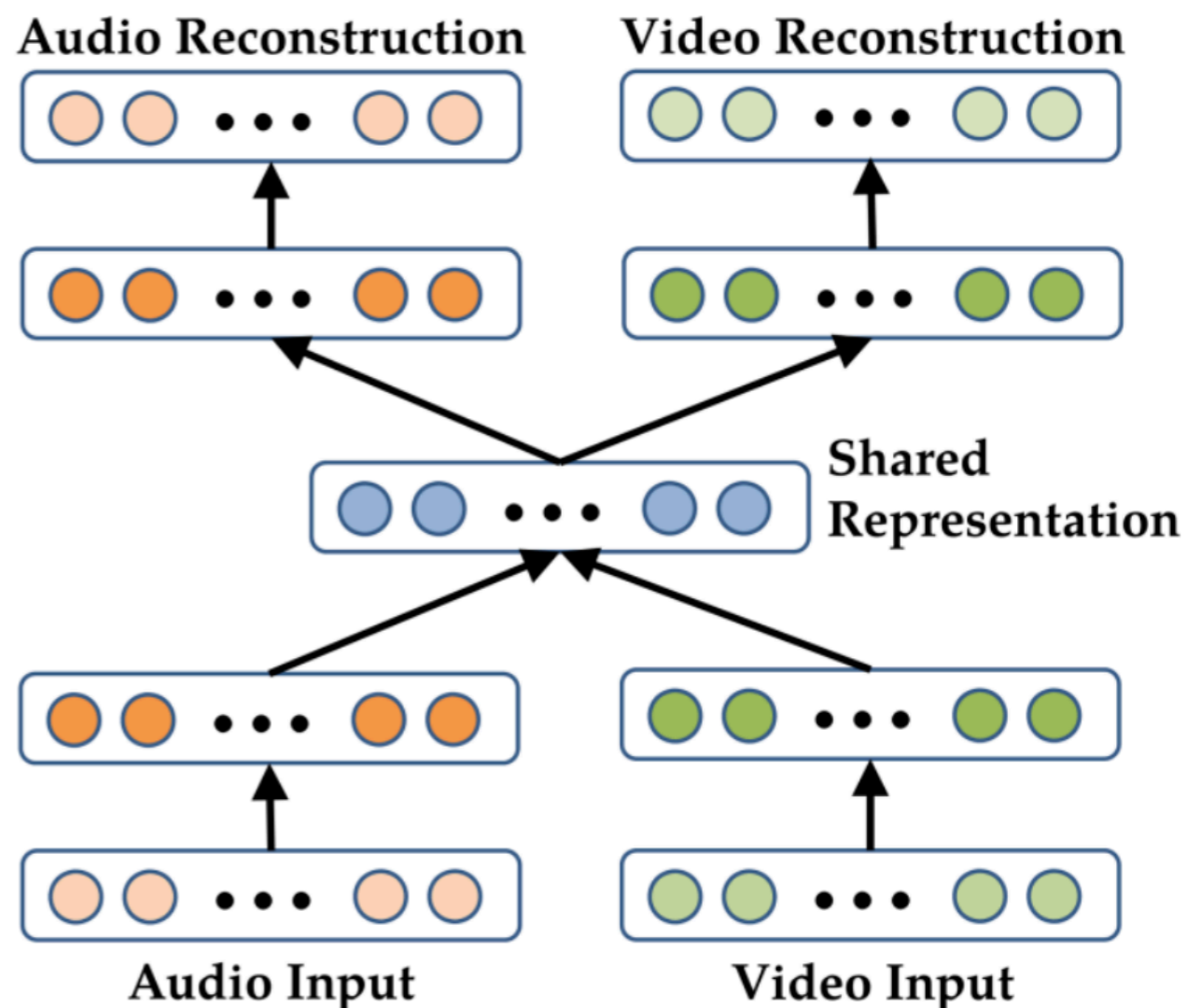
Joint Multimodal Representations

- Audio-visual speech recognition (Ngiam et al. 2011)
 - Bimodal Deep Belief Network
- Image captioning (Srivastava, Salahutdinov, 2012)
 - Multimodal Deep Boltzmann Machine
- Audio-visual emotion recognition (Kim et al. 2013)
 - Deep Boltzmann Machine



Deep Multimodal Autoencoder

- Bimodal auto-encoder
 - Used for audio-visual speech recognition
- Individual modalities can be pretrained
 - RBMs
 - Denoising Autoencoders
- Train the model to reconstruct the other modality
 - Use both
 - Remove audio
 - Remove video



Multimodal Vector Space Arithmetic

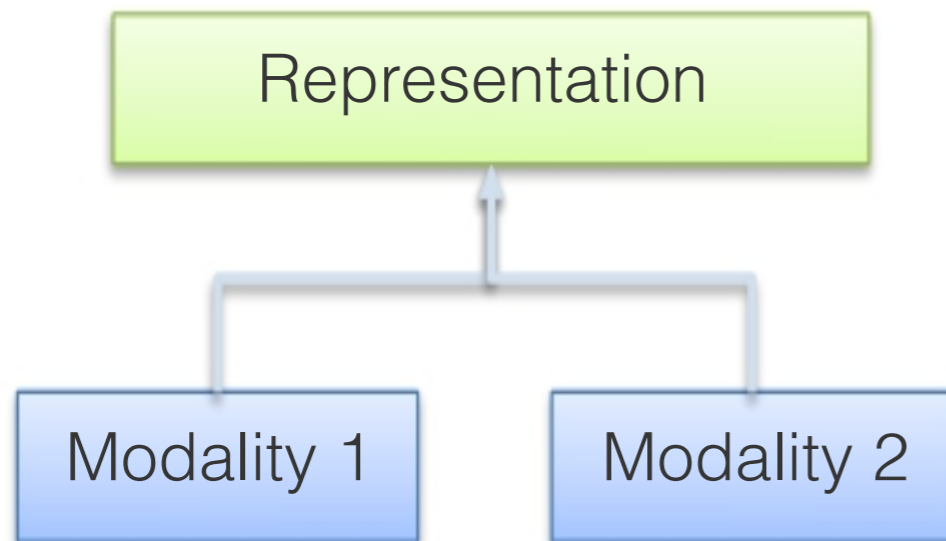
- Obtain a vector by the image embedding of a blue car - word embedding of “blue” + word embedding of “red”
- Retrieve the nearest images



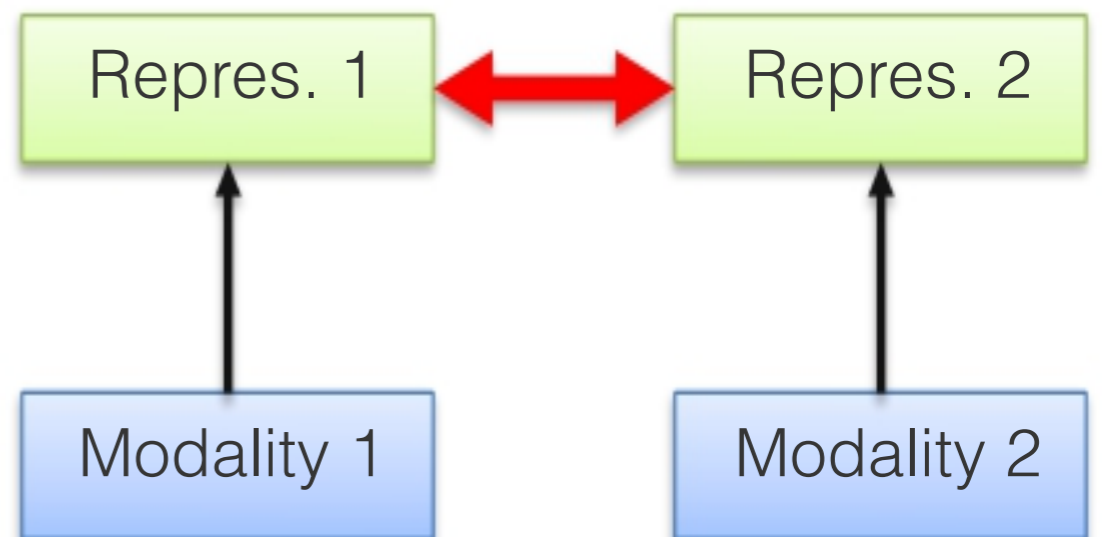
Core Challenge 1: Representation

- **Definition:** Learning how to represent and summarize multimodal data in a way that exploits the complementarity and redundancy.

A Joint representations:



B Coordinated representations:

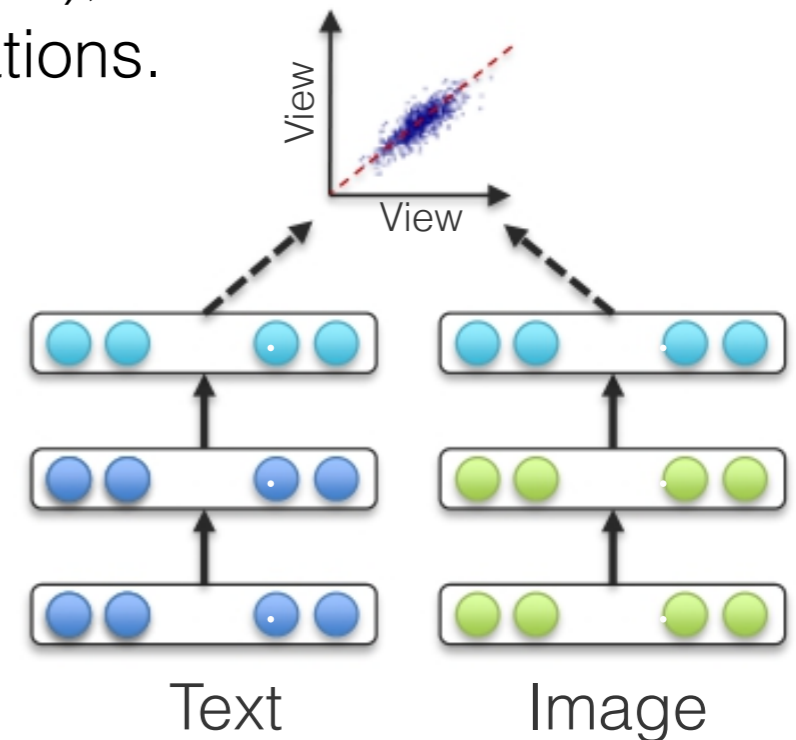


Coordinated Representation: Deep CCA

- Learn linear projections that are maximally correlated:

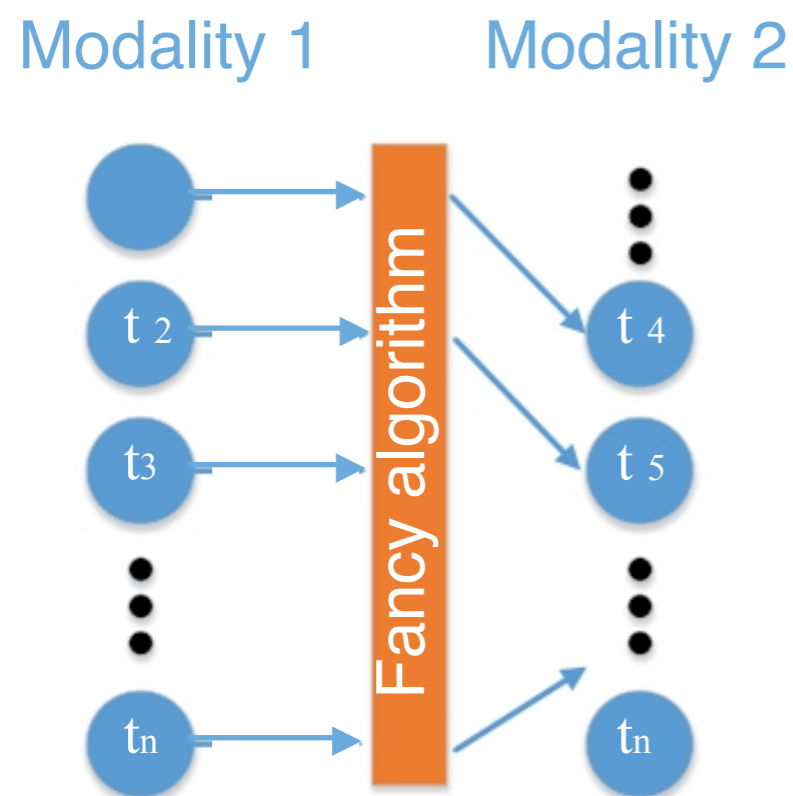
$$(\theta_1^*, \theta_2^*) = \underset{(\theta_1, \theta_2)}{\operatorname{argmax}} \operatorname{corr}(f_1(X_1; \theta_1), f_2(X_2; \theta_2)).$$

where f_1 and f_2 are two encoders (e.g., for texts, images),
corr computes the correlation between two representations.



Core Challenge 2: Alignment

- Definition: Identify the direct relations between (sub)elements from two or more different modalities



A Explicit Alignment

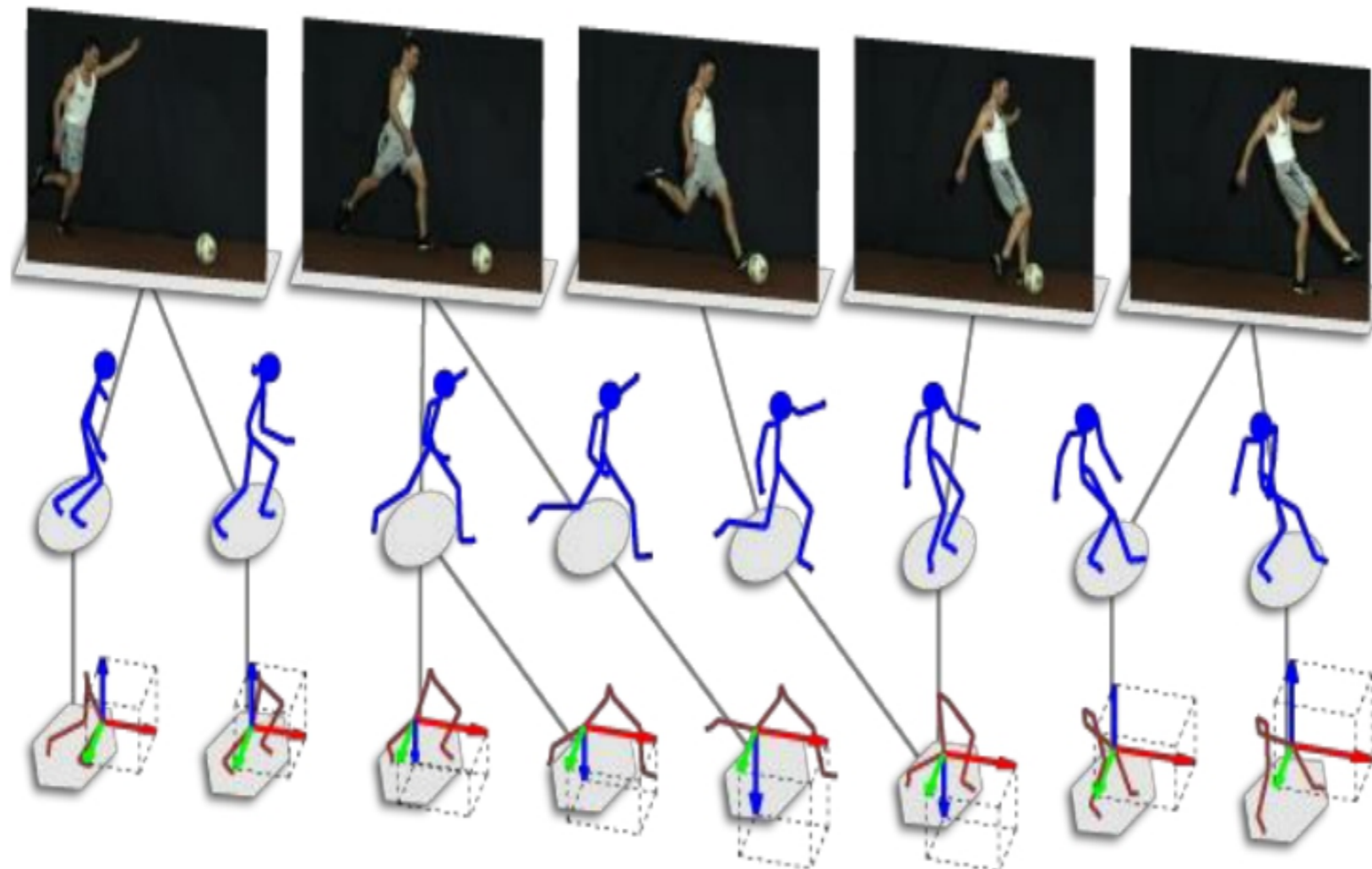
The goal is to directly find correspondences between elements of different modalities

B Implicit Alignment

Uses internally latent alignment of modalities in order to better solve a different problem

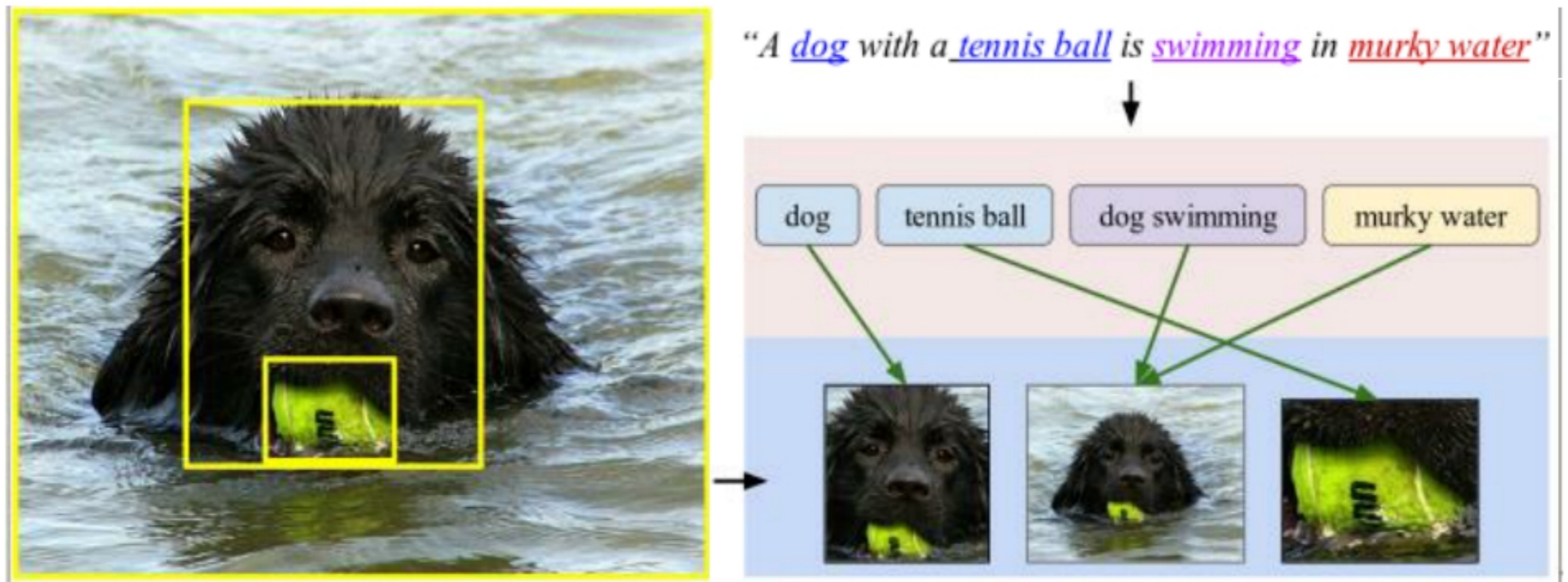
Example: Temporal Sequence Alignment

- Application:
 - Re-aligning asynchronous data
 - Finding similar data across modalities
 - Event reconstruction from multiple sources



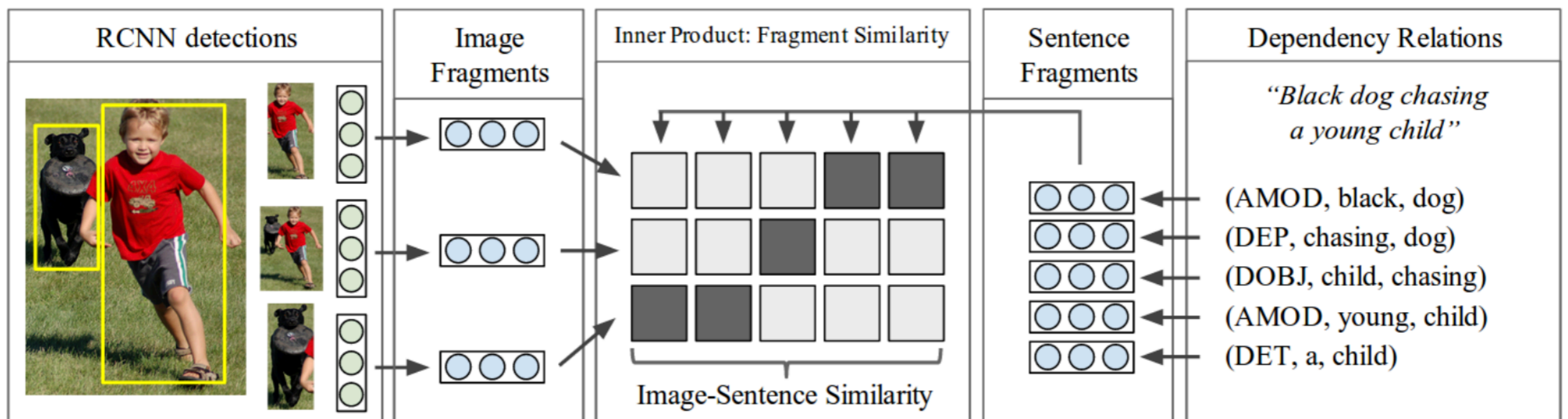
Implicit Alignment

- Vision-language alignment, a.k.a. visual grounding.



Implicit Alignment

- Use object detection (RCNN) tools to extract bounding boxes, and encode each bounding box
- Use dependency parsing to extract dependency relations (Relation-head-tail triple), and encode each relation
- Compute the similarity and optimize the alignment objectives.

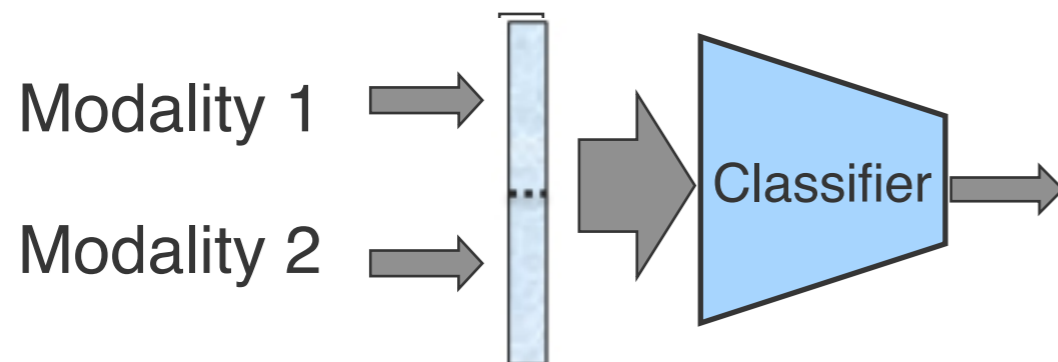


Core Challenge 3: Fusion

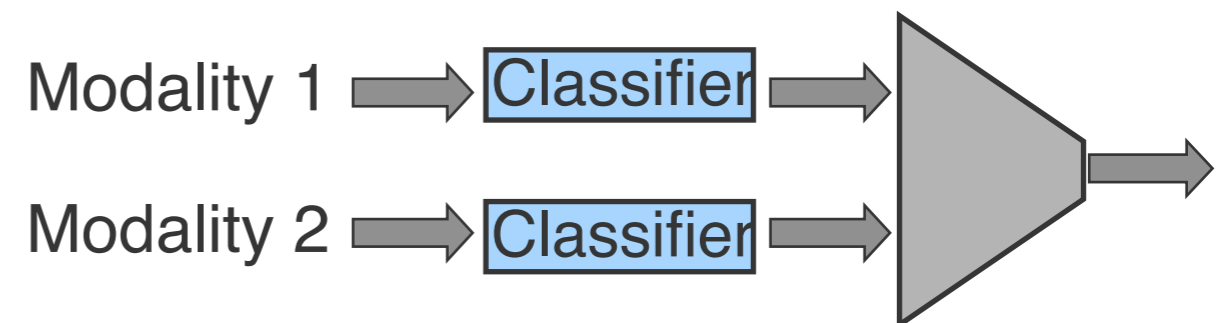
- **Definition:** To join information from two or more modalities to perform a prediction task.

A Model-Agnostic Approaches

1) Early Fusion



2) Late Fusion



Core Challenge 3: Fusion

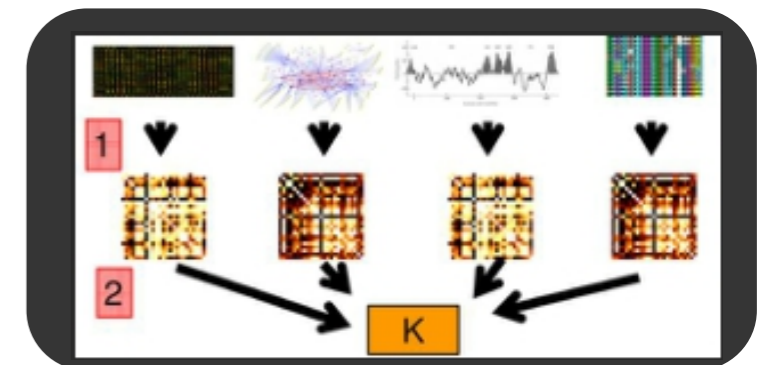
- **Definition:** To join information from two or more modalities to perform a prediction task.

A Model-Based (Intermediate) Approaches

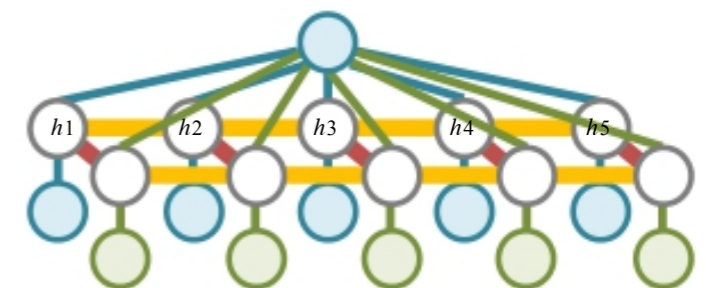
1) Deep neural networks

2) Kernel-based methods

3) Graphical models



Multiple kernel learning

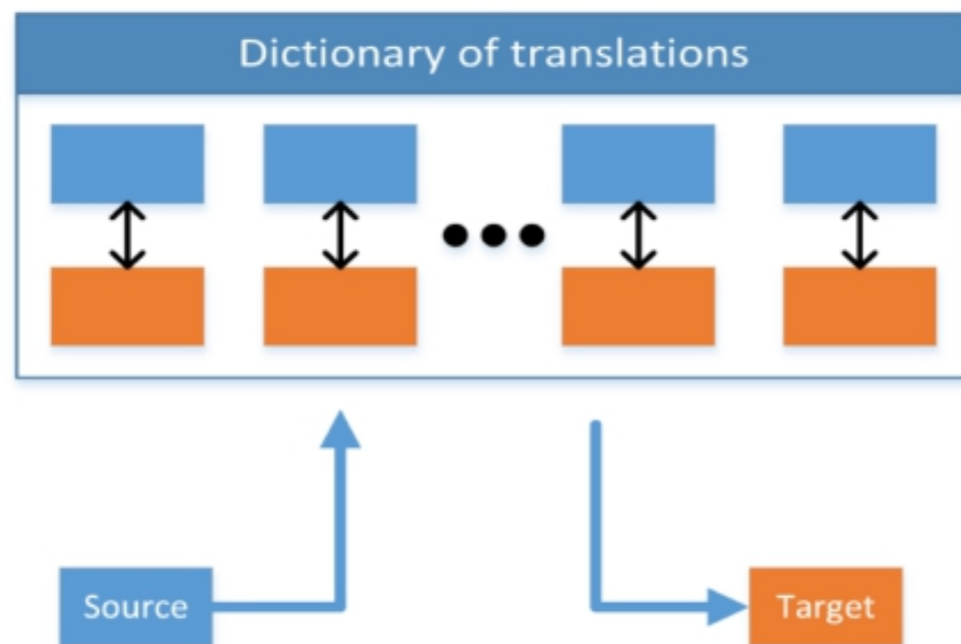


Multi-View Hidden CRF

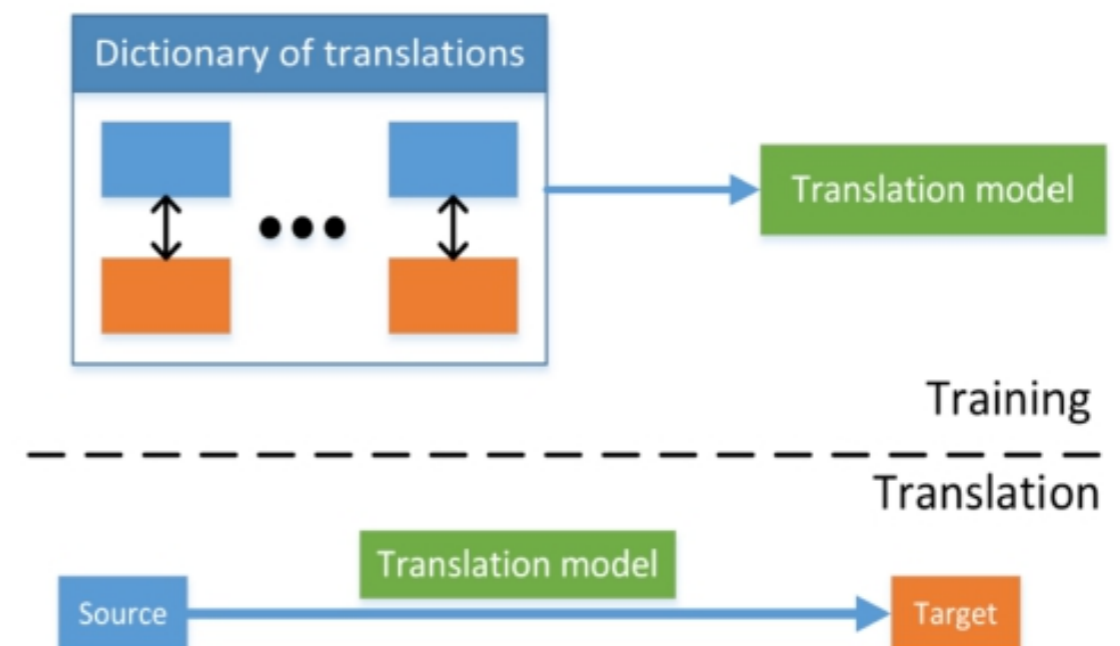
Core Challenge 4: Translation

- **Definition:** Process of changing data from one modality to another, where the translation relationship can often be open-ended or subjective

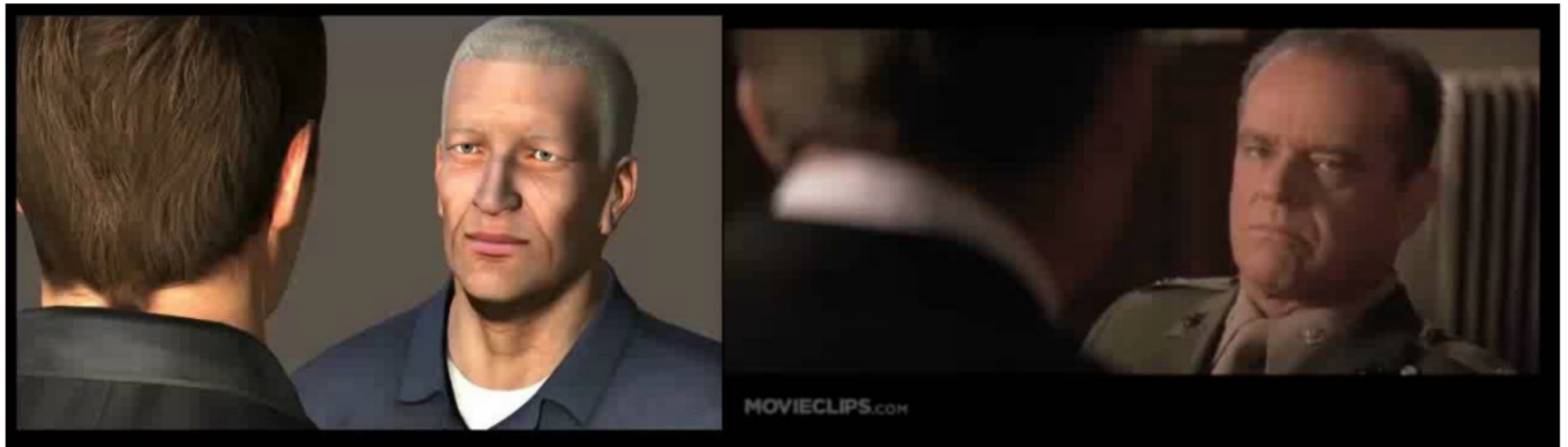
A Example-based



A Model-based



Text+Audio to Vision Translation



Visual gestures
(both speaker and
listener gestures)

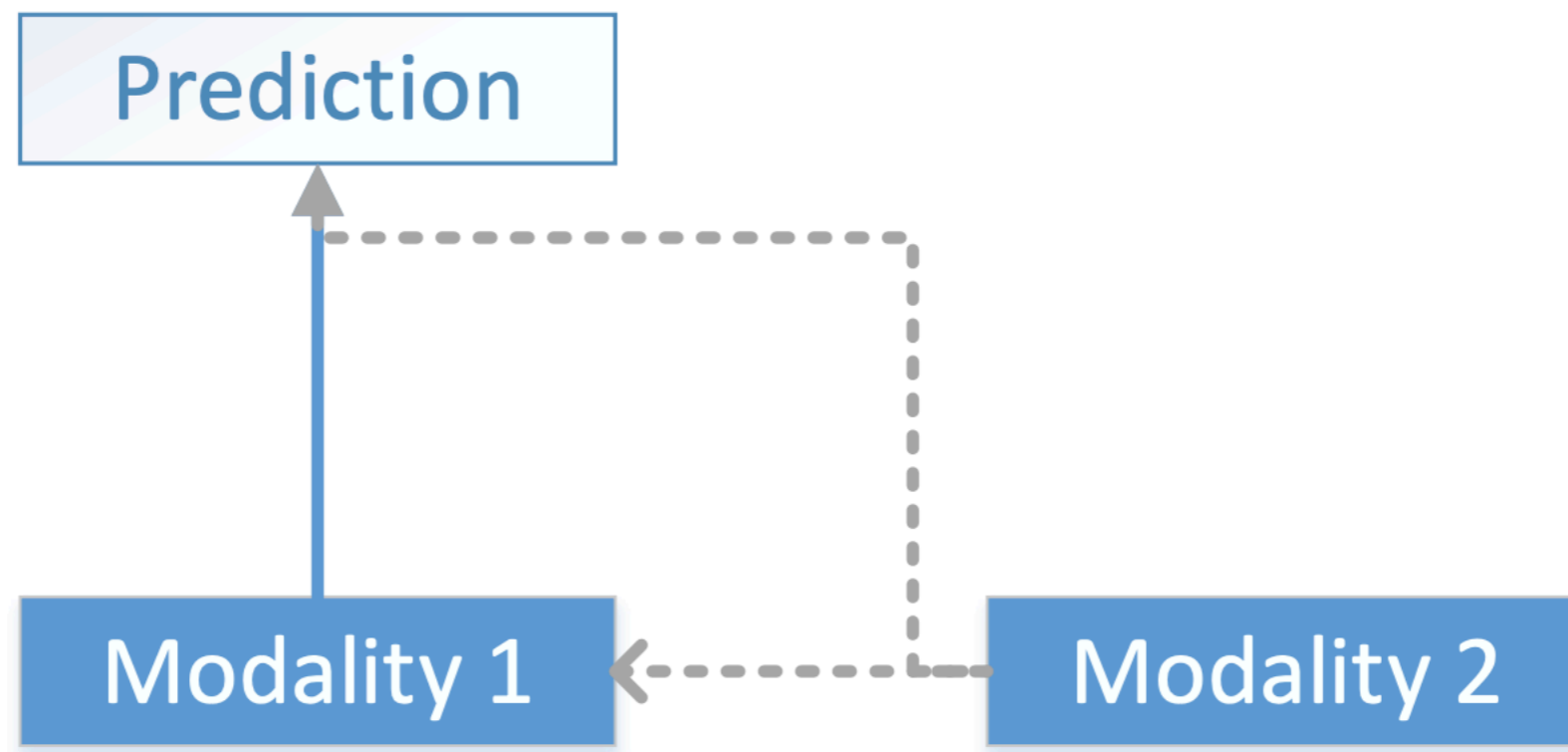


Transcriptions
+
Audio streams

Marsella et al., Virtual character performance from speech, SIGGRAPH/ Eurographics Symposium on Computer Animation, 2013

Core Challenge 5: Co-Learning

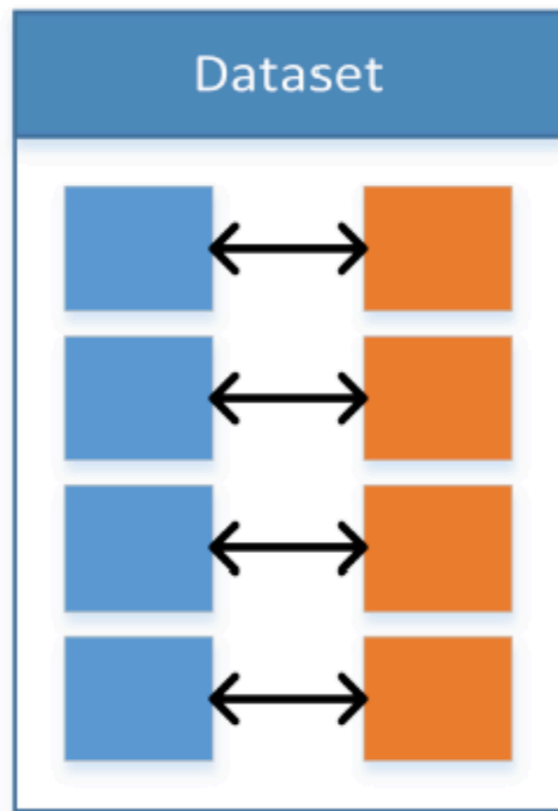
- **Definition:** Transfer knowledge between modalities, including their representations and predictive models.



Core Challenge 5: Co-Learning

- Three data settings.

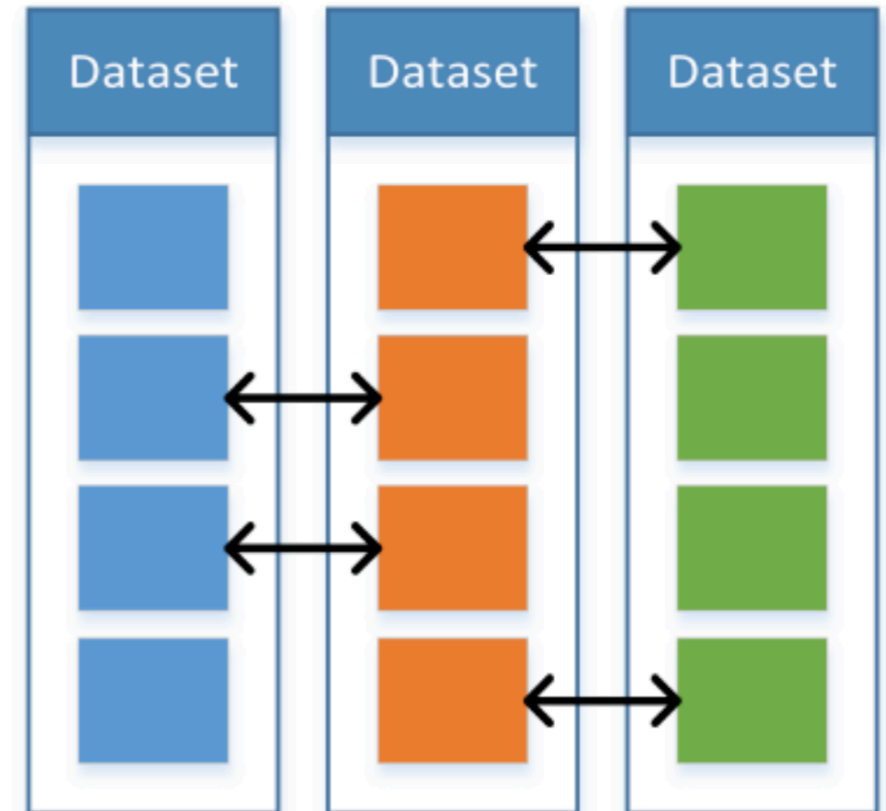
(A) Parallel



(B) Non-Parallel



(C) Hybrid



Taxonomy of Multimodal Research

Representation

- Joint
 - *Neural networks*
 - *Graphical models*
 - *Sequential*
- Coordinated
 - *Similarity*
 - *Structured*

Translation

- Example-based
 - *Retrieval*
 - *Combination*
- Model-based
 - *Grammar-based*

- *Encoder-decoder*
- *Online prediction*

Alignment

- Explicit
 - *Unsupervised*
 - *Supervised*
- Implicit
 - *Graphical models*
 - *Neural networks*

Fusion

- Model agnostic
 - *Early fusion*
 - *Late fusion*
 - *Hybrid fusion*

- Model-based
 - *Kernel-based*
 - *Graphical models*
 - *Neural networks*

Co-learning

- Parallel data
 - *Co-training*
 - *Transfer learning*
- Non-parallel data
 - *Zero-shot learning*
 - *Concept grounding*
 - *Transfer learning*
- Hybrid data
 - *Bridging*

Multimodal Applications

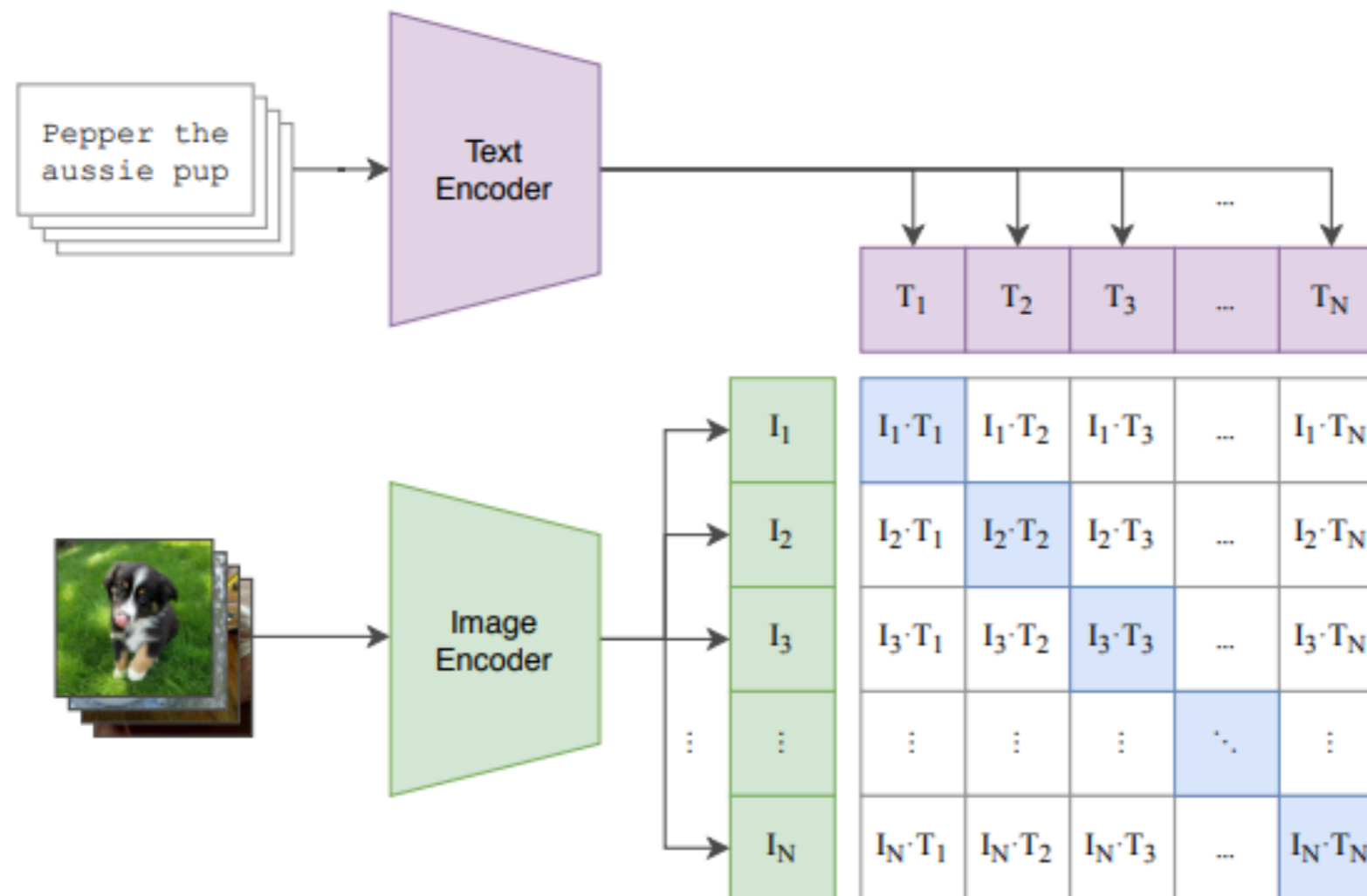
APPLICATIONS	CHALLENGES				
	REPRESENTATION	TRANSLATION	FUSION	ALIGNMENT	CO-LEARNING
Speech Recognition and Synthesis					
Audio-visual Speech Recognition	✓		✓	✓	✓
(Visual) Speech Synthesis	✓	✓			
Event Detection					
Action Classification	✓		✓		✓
Multimedia Event Detection	✓		✓		✓
Emotion and Affect					
Recognition	✓		✓	✓	✓
Synthesis	✓	✓			
Media Description					
Image Description	✓	✓		✓	✓
Video Description	✓	✓	✓	✓	✓
Visual Question-Answering	✓		✓	✓	✓
Media Summarization	✓	✓	✓		
Multimedia Retrieval					
Cross Modal retrieval	✓	✓		✓	✓
Cross Modal hashing	✓				✓

Recent Pre-trained Vision- Language Models

CLIP

- Pre-train V+L models using image captioning data (i.e., image-text pairs) by contrastive loss

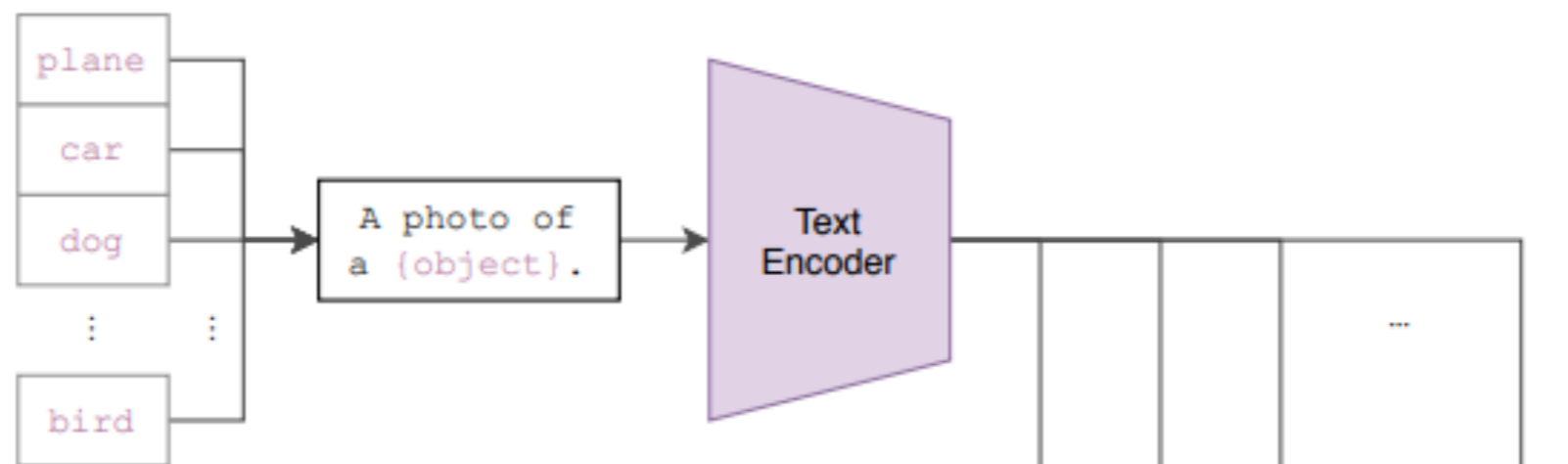
(1) Contrastive pre-training



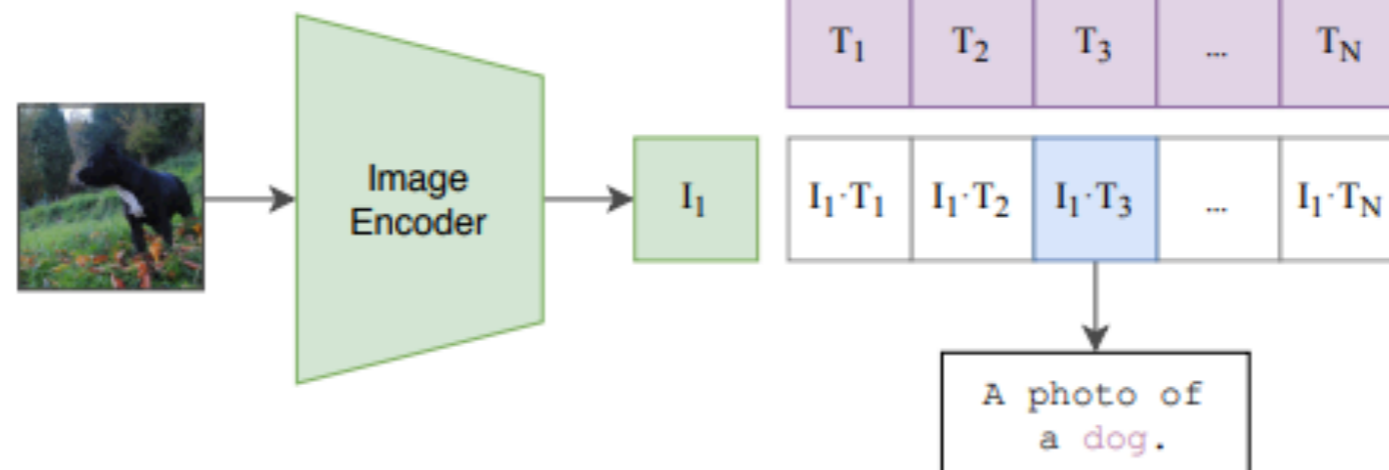
CLIP: Zero-shot Image Classification

- Use a template + class label string to create a sentence

(2) Create dataset classifier from label text



(3) Use for zero-shot prediction



CLIP: pseudocode

```
# image_encoder - ResNet or Vision Transformer
# text_encoder  - CBOW or Text Transformer
# I[n, h, w, c] - minibatch of aligned images
# T[n, l]       - minibatch of aligned texts
# W_i[d_i, d_e] - learned proj of image to embed
# W_t[d_t, d_e] - learned proj of text to embed
# t             - learned temperature parameter

# extract feature representations of each modality
I_f = image_encoder(I) #[n, d_i]
T_f = text_encoder(T)  #[n, d_t]

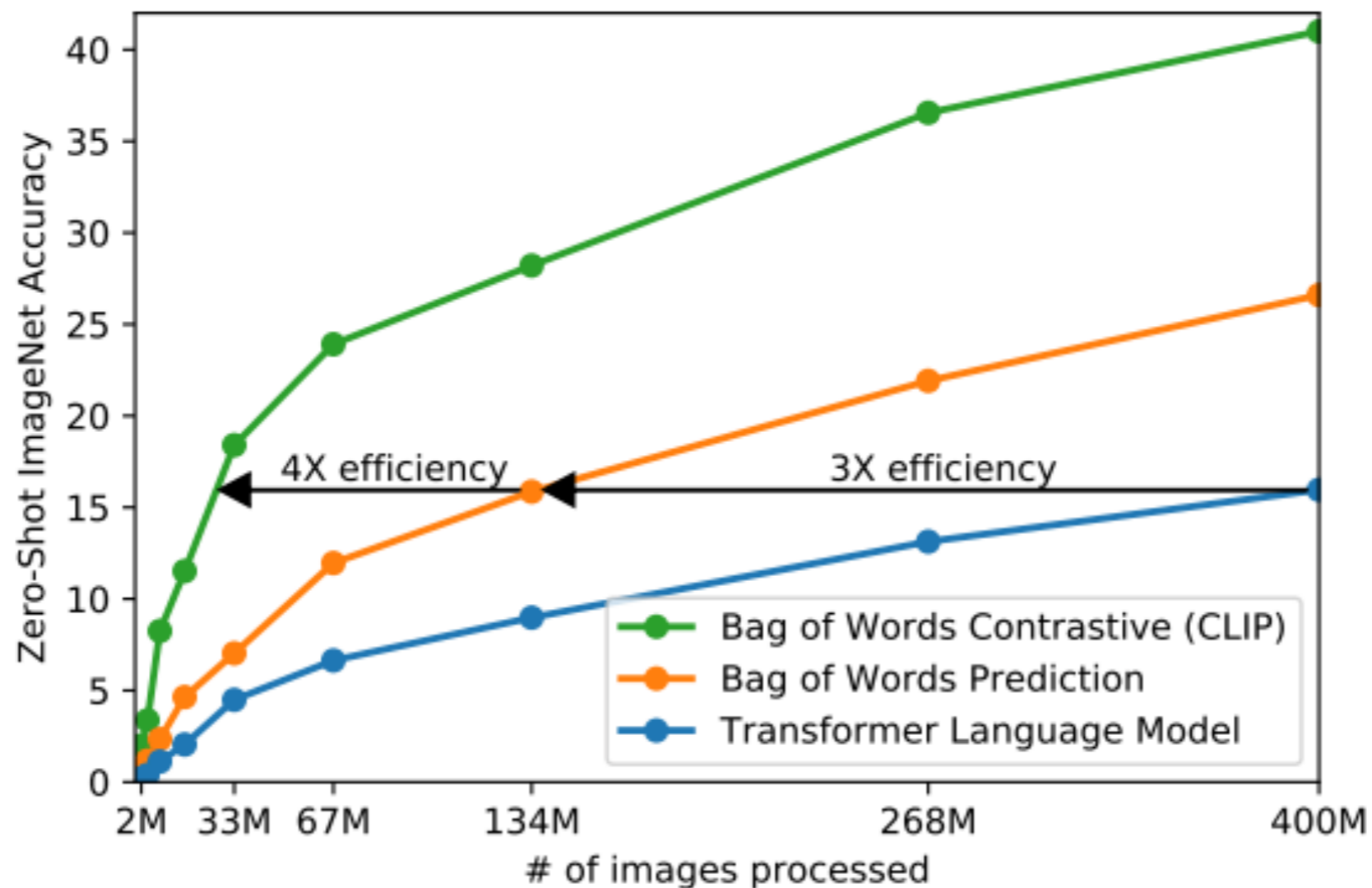
# joint multimodal embedding [n, d_e]
I_e = l2_normalize(np.dot(I_f, W_i), axis=1)
T_e = l2_normalize(np.dot(T_f, W_t), axis=1)

# scaled pairwise cosine similarities [n, n]
logits = np.dot(I_e, T_e.T) * np.exp(t)

# symmetric loss function
labels = np.arange(n)
loss_i = cross_entropy_loss(logits, labels, axis=0)
loss_t = cross_entropy_loss(logits, labels, axis=1)
loss   = (loss_i + loss_t)/2
```

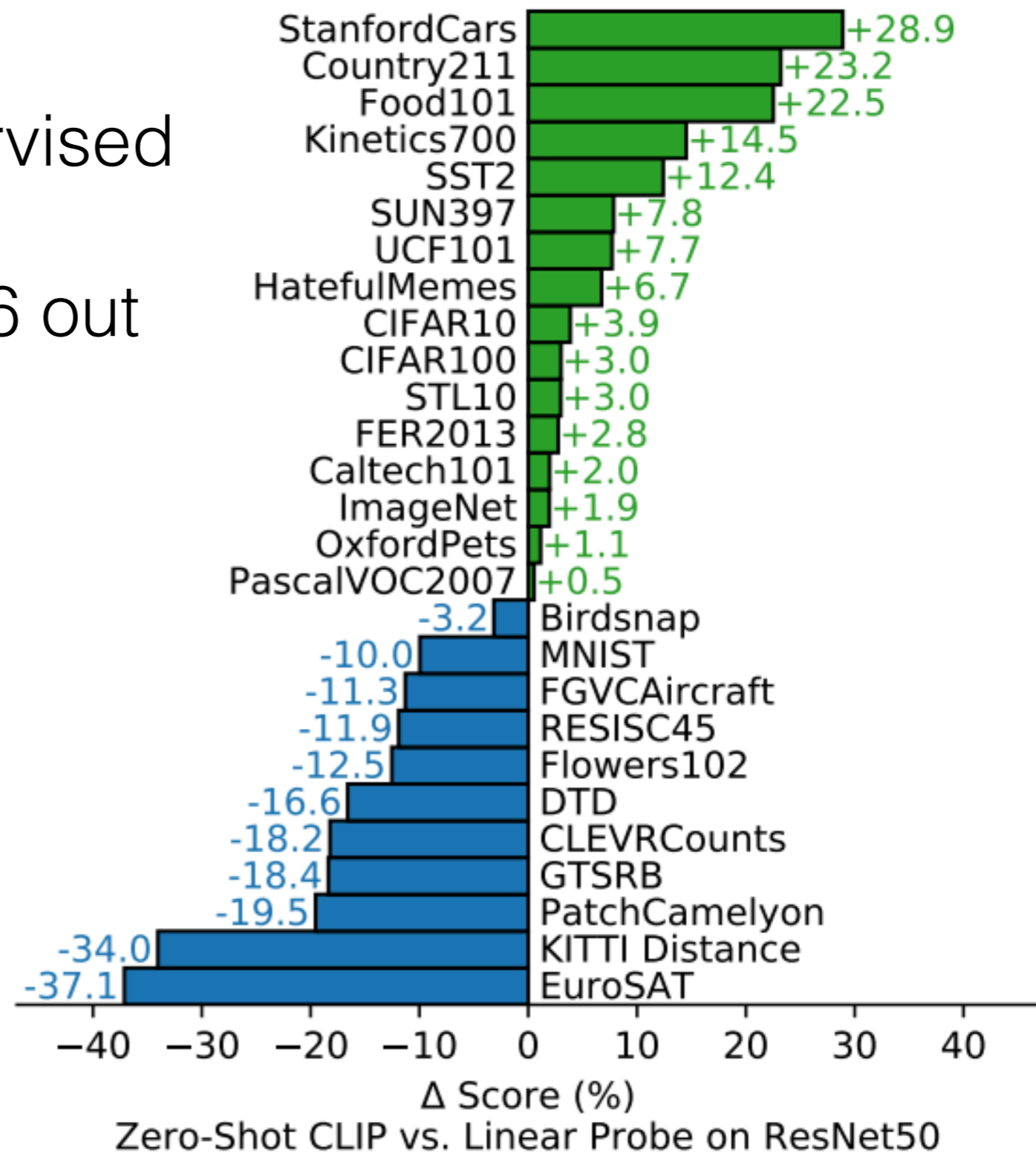
Efficiency of BoW Representations

- CLIP w/ BoW representations work better than transformer language model on zero-shot ImageNet prediction



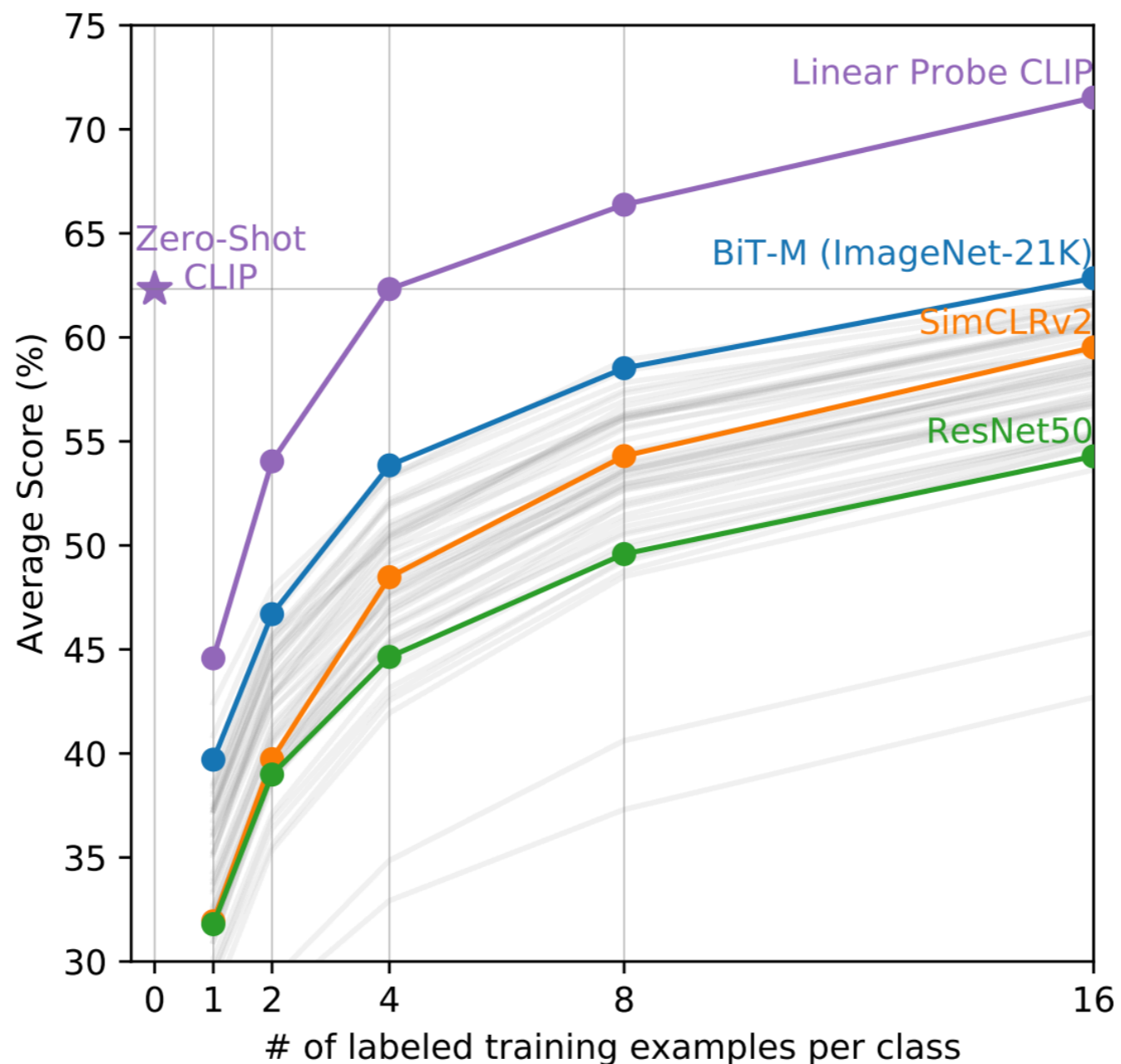
Zero-shot Image Classification

- Zero-shot CLIP classifier outperforms a fully supervised linear classifier fitted on ResNet-50 features on 16 out of 27 datasets (including ImageNet).



Few-shot Performance

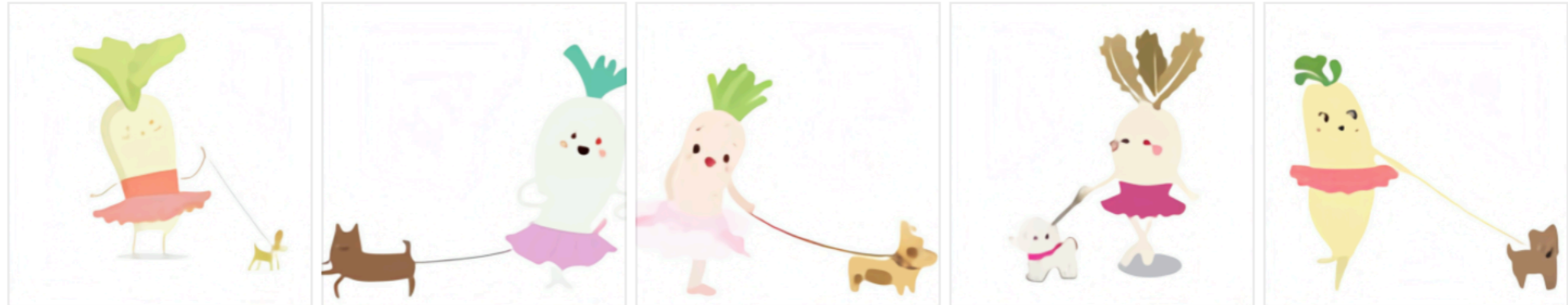
- Zero-shot CLIP outperforms other few-shot baselines
- Few-shot CLIP further improves w/ a few labeled data.



DALL-E: Text-to-Image Generation

TEXT PROMPT an illustration of a baby daikon radish in a tutu walking a dog

AI-GENERATED IMAGES



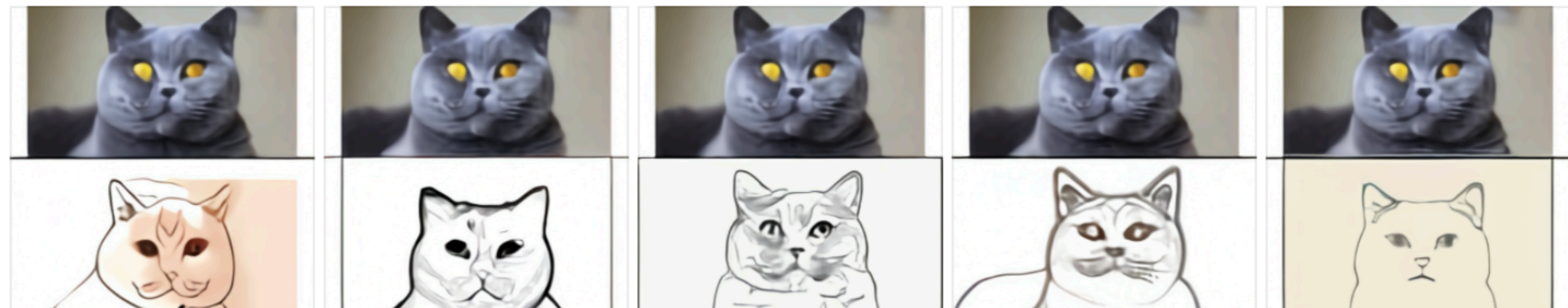
TEXT PROMPT a store front that has the word 'openai' written on it. . . .

AI-GENERATED IMAGES



TEXT & IMAGE PROMPT the exact same cat on the top as a sketch on the bottom

AI-GENERATED IMAGES



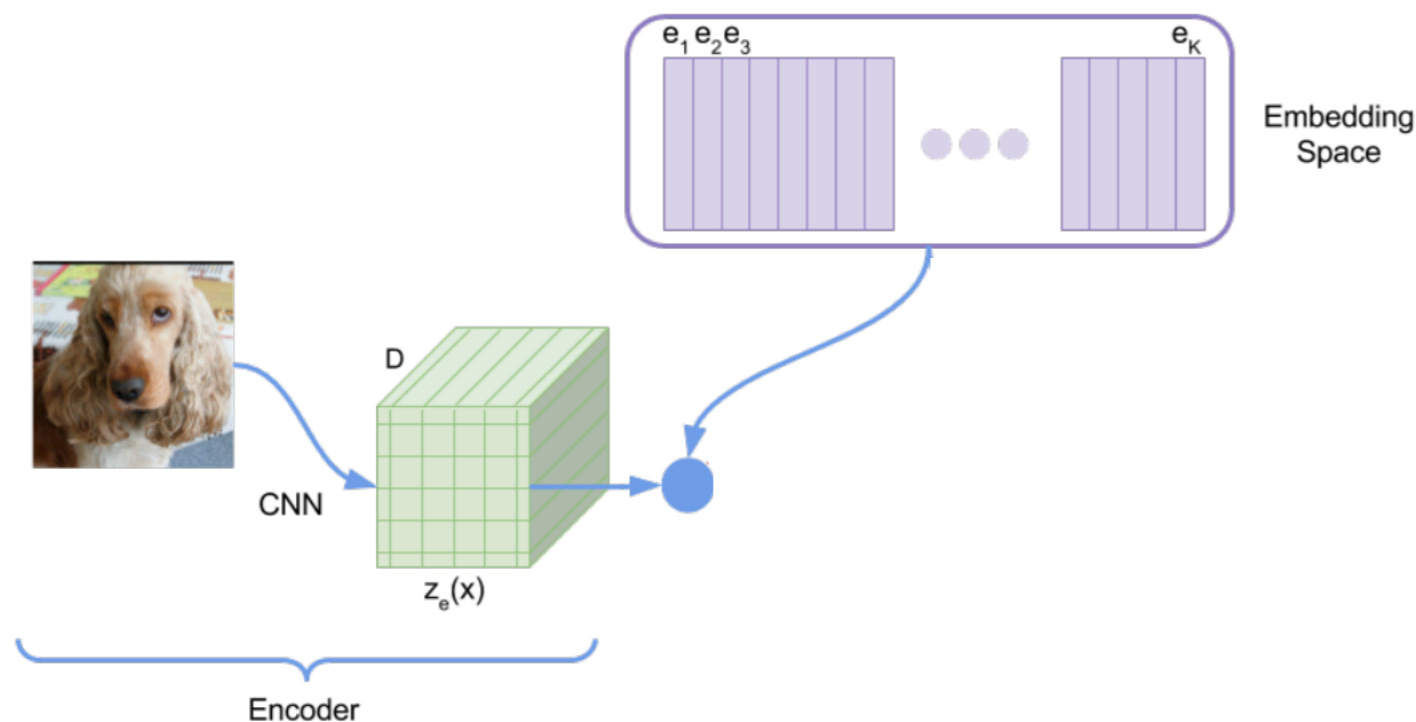
DALL-E

- **Stage 1:** Train a discrete VAE on **only images** (encode RGB images to image tokens (latent variable), and decode image tokens back to RGB images)
- **Stage 2:** Train a language model (LM) to generate a combined sequence of **both text tokens and image tokens**

DALL-E: dVAE Training

- **Stage 1:** Train a discrete variational autoencoder (dVAE or VQ-VAE, Oord et al. 2018) to compress each 256x256 RGB image into 32x32 grid of image tokens.

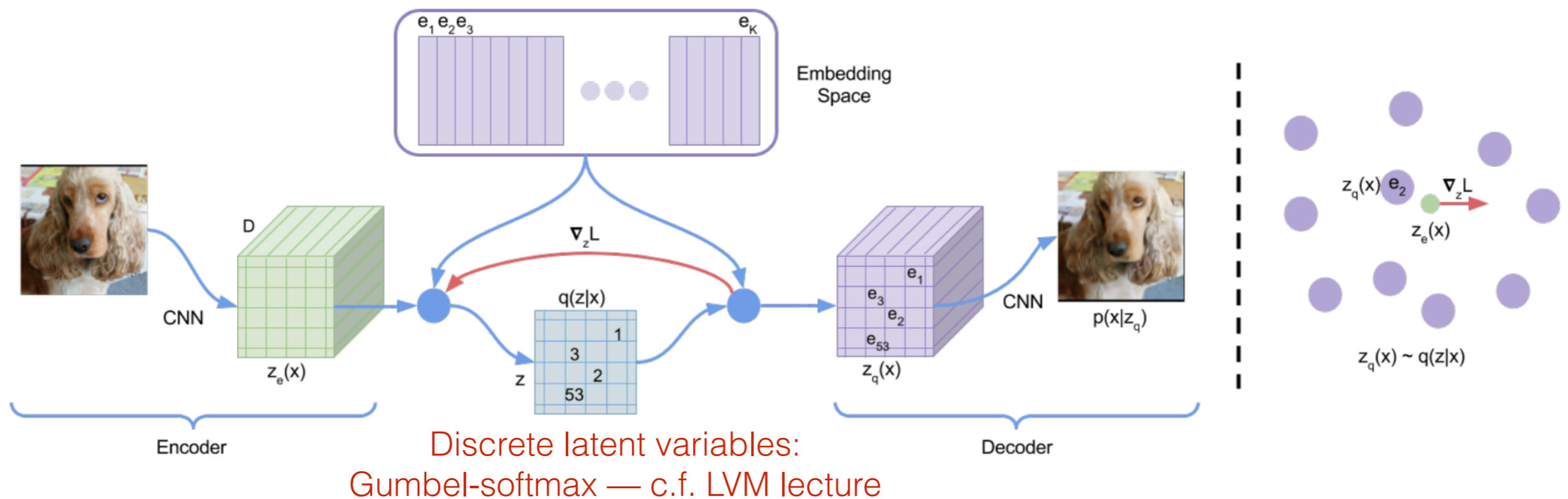
Each image token finds the nearest vector from a 8196 codebook (vocabulary)



DALL-E: dVAE Training

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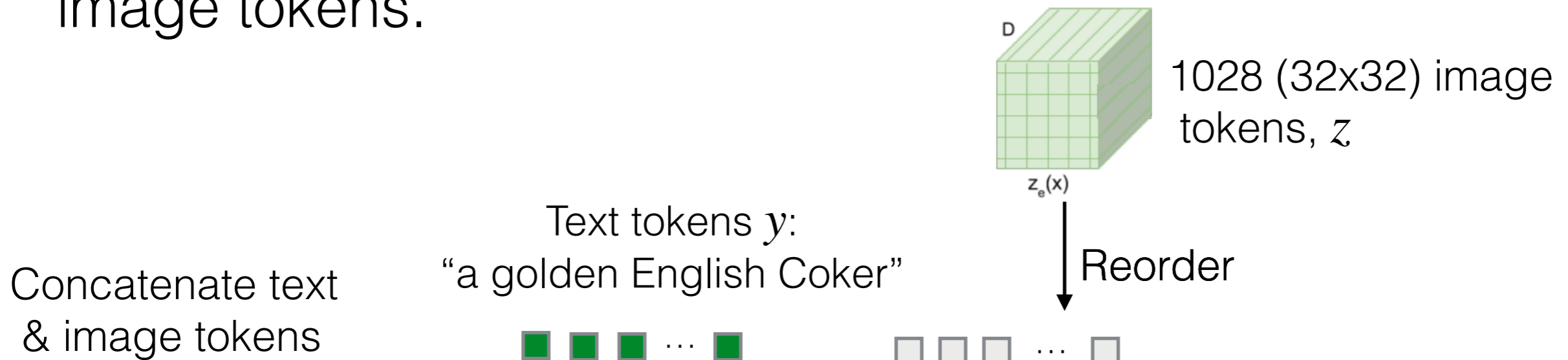


VAE training:

Maximize Evidence Lower Bound

DALL-E: Language Model Training

- **Stage 2:** Concatenate up to 256 text tokens with the 32x32 (=1024) image tokens, and train an autoregression transformer to model the joint distribution of the text and image tokens.

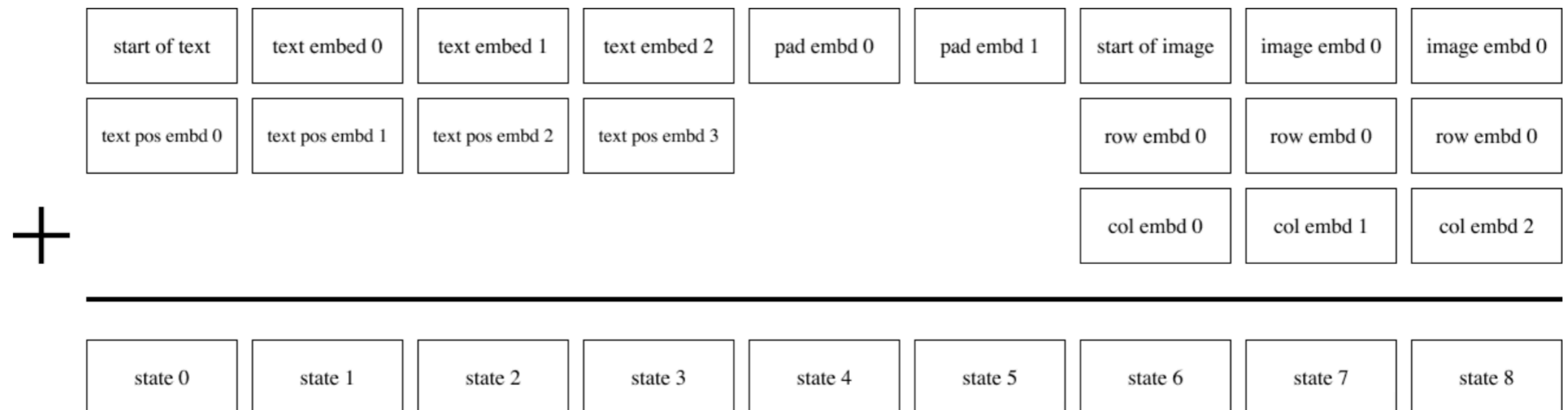


Autoregressive LM training:
Maximum Likelihood Estimation

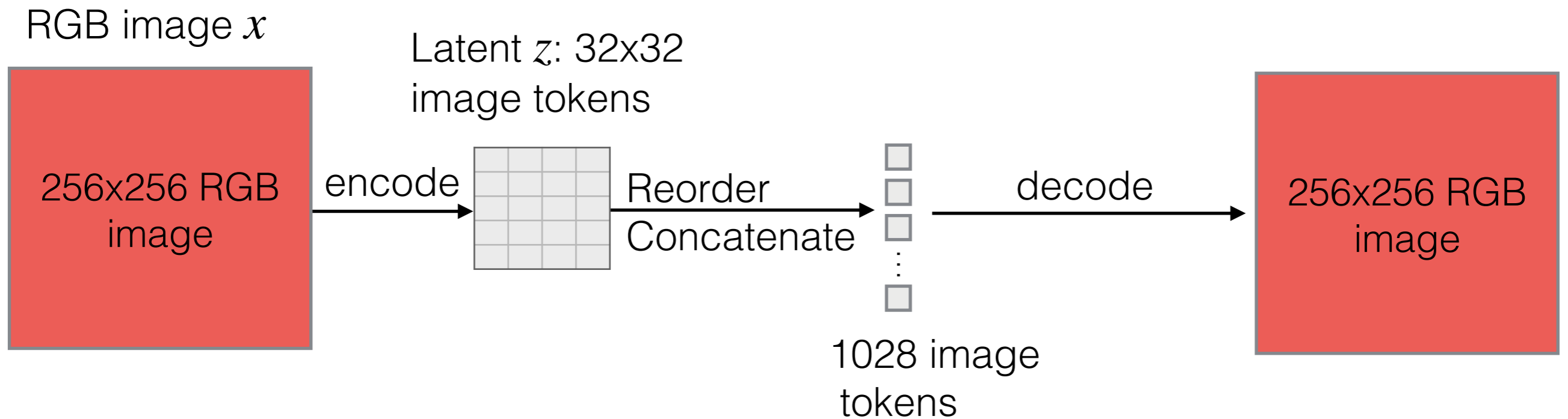
$$\max_{\psi} p_{\psi}(y, z)$$

DALL-E: Language Model Training

- Representation of the combined text + image token sequence



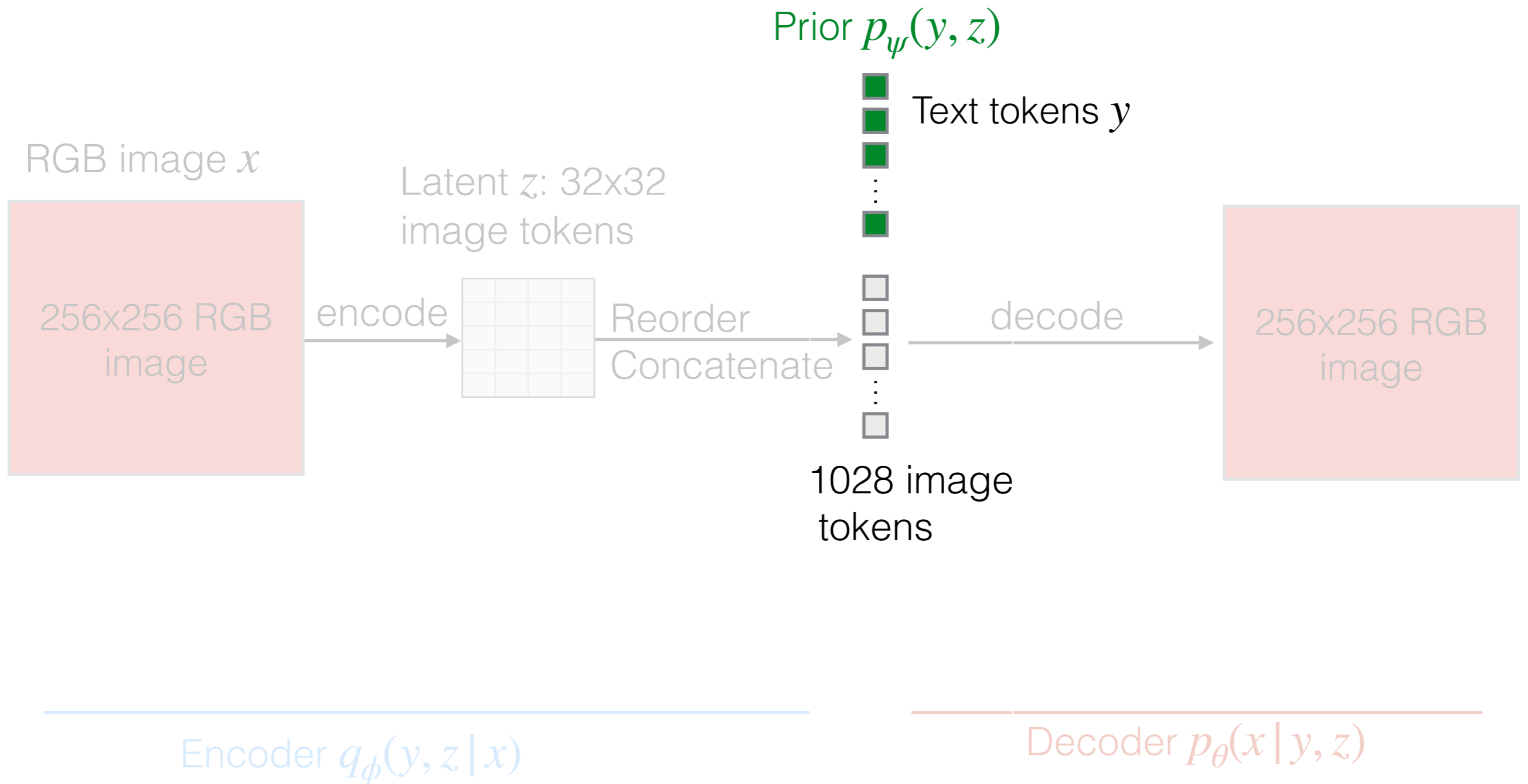
DALL-E: Stage 1



Encoder $q_{\phi}(y, z | x)$

Decoder $p_{\theta}(x | y, z)$

DALL-E: Stage 2



DALL-E: Overall Training Procedure

Maximize Evidence Lower Bound (ELB)— LVM lecture

$$\ln p_{\theta, \psi}(x, y) \geq \mathbb{E}_{z \sim q_{\phi}(z | x)} \left(\ln p_{\theta}(x | y, z) - \beta D_{\text{KL}}(q_{\phi}(y, z | x), p_{\psi}(y, z)) \right),$$

Stage 1 updates p_{θ} , q_{ϕ} and fixes p_{ψ}

Stage 2 fixes p_{θ} , q_{ϕ} and updates p_{ψ}

- x : the RGB image (256x256)
- z : the 32x32 (=1024) image tokens
- y : the text up to 256 tokens
- q_{ϕ} is the distribution over text tokens and the 32x32 image tokens generated by dVAE encoder given the RGB image x
- p_{θ} is the distribution over the RGB image generated by dVAE decoder given the image tokens and text tokens
- p_{ψ} is the prior distribution over the text and image tokens.

DALL-E: Test Time

- Given a text prompt y , use the prior distribution (LM) to sample a sequence of 1028 image tokens
- Re-order 1028 image tokens to 32x32 shape
- Use dVAE's decoder to generate a RGB image from the image tokens.

Text-to-Image Generation

a very cute cat laying by a big bike.

china airlines plain on the ground at an airport with baggage cars nearby.

a table that has a train model on it with other cars and things

a living room with a tv on top of a stand with a guitars sitting next to

a couple of people are sitting on a wood bench

a very cute giraffe making a funny face.

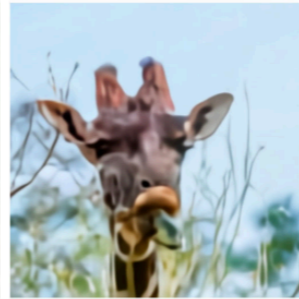
a kitchen with a fridge, stove and sink

a group of animals are standing in the snow.

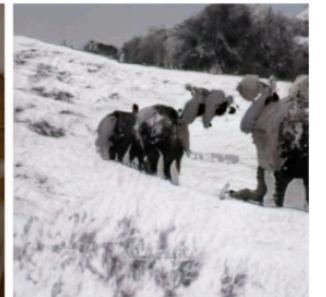
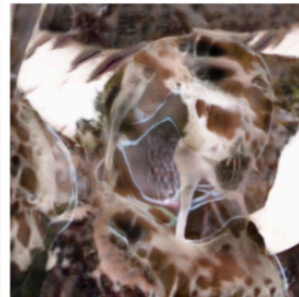
Validation



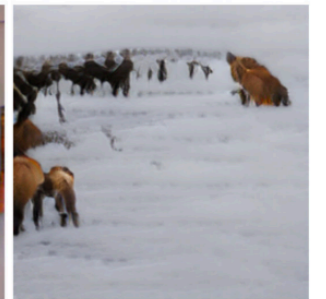
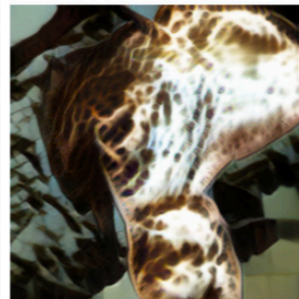
Ours



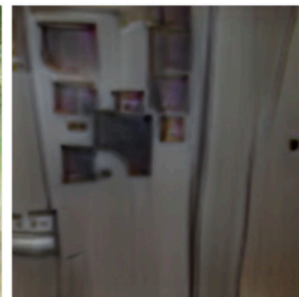
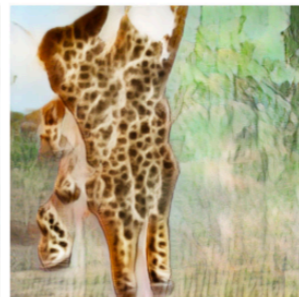
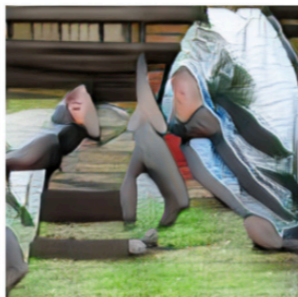
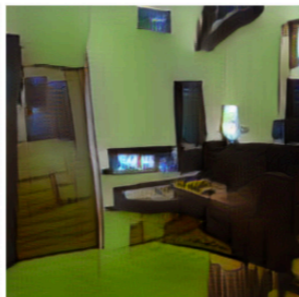
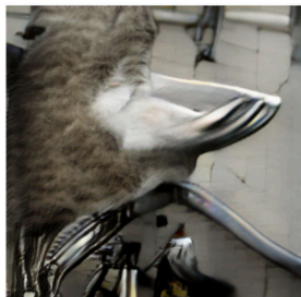
DF-GAN



DM-GAN

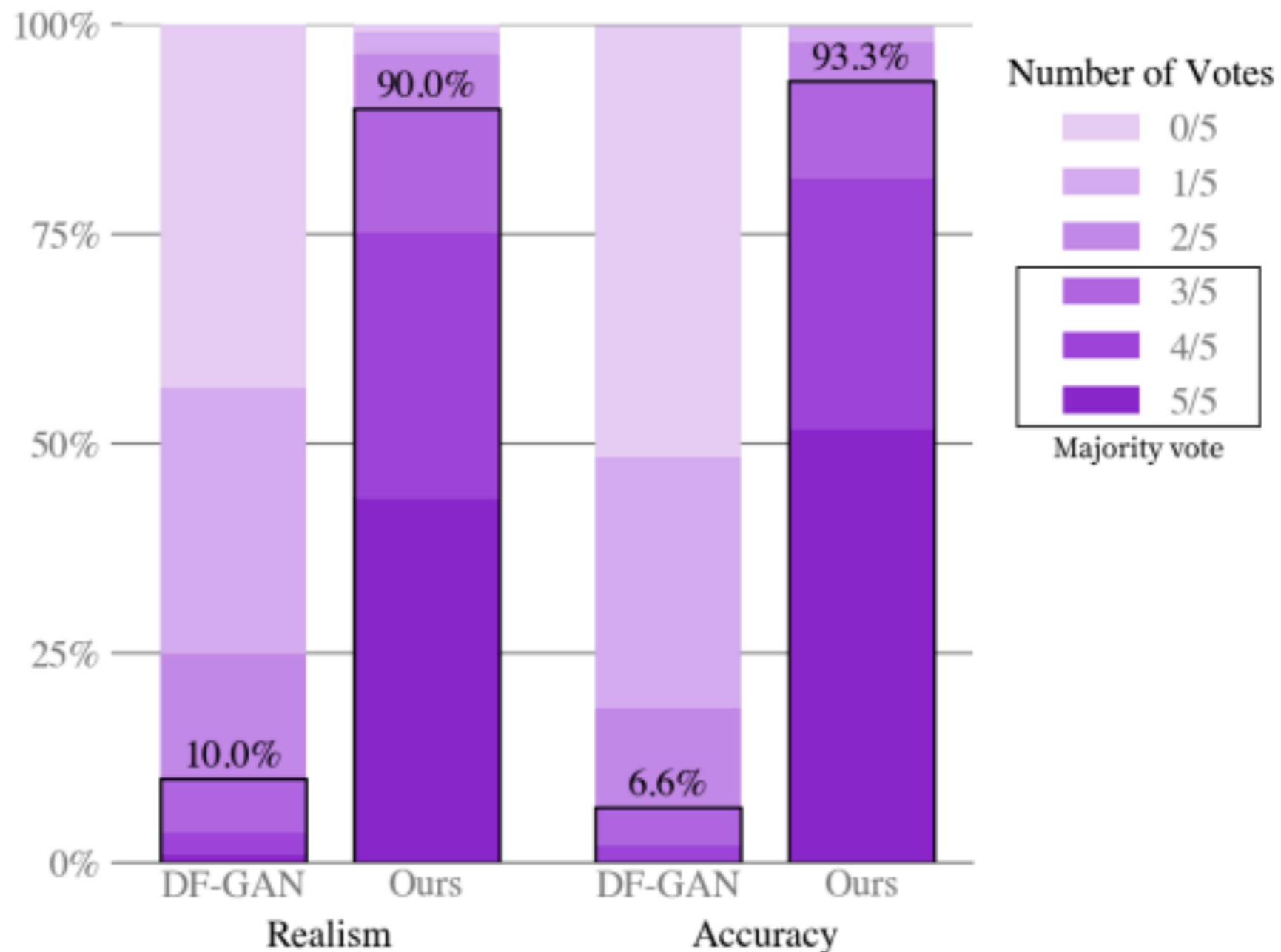


AttnGAN



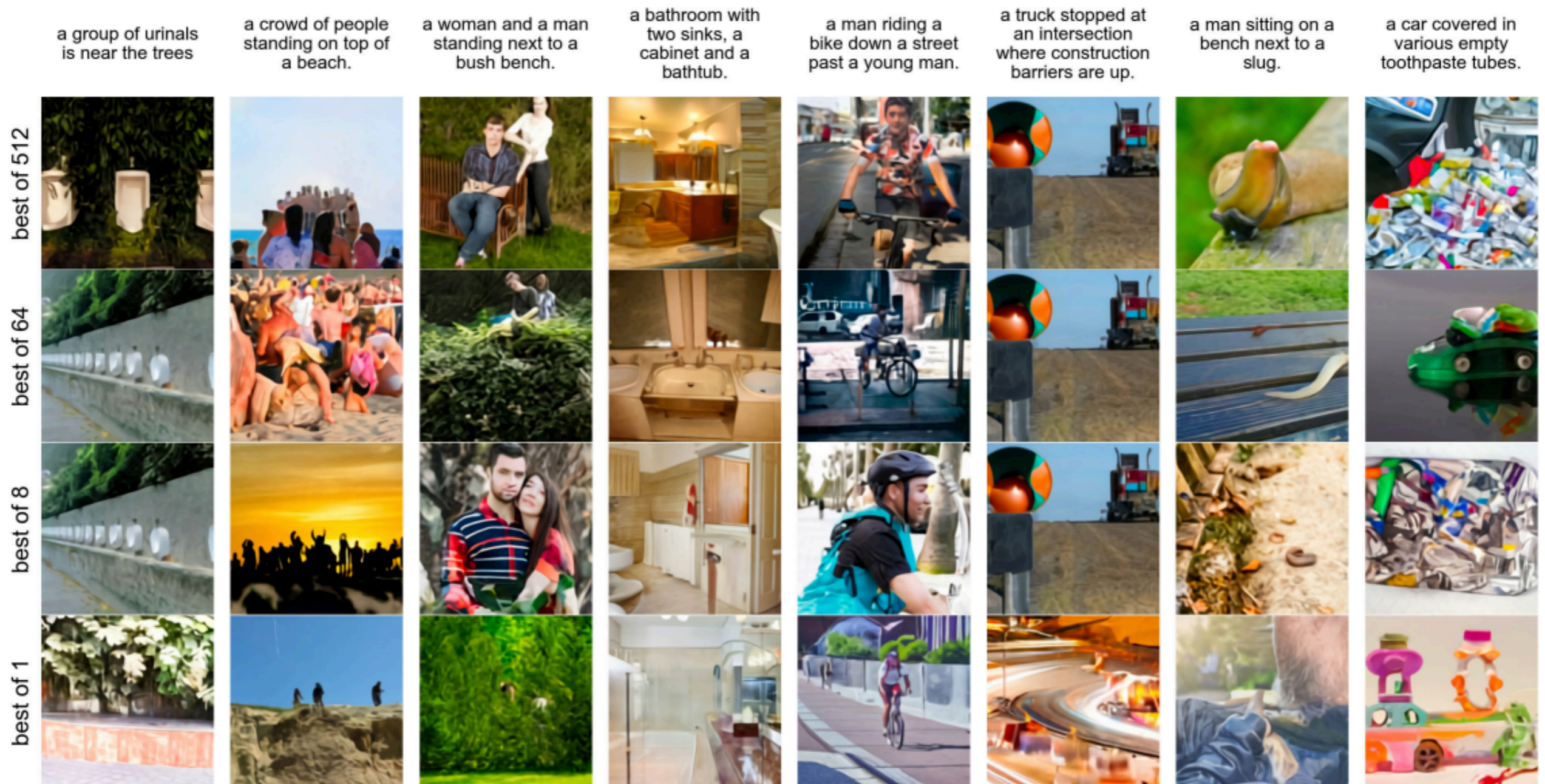
Human Eval on “Realism” and “Accuracy”

- DALL-E outperforms DF-GAN



Sample, then Re-rank

- Sample K (e.g., $K=1, 8, 64, 512$) images from DALL-E, re-rank by CLIP, and pick the best output.



Questions?